

<u>More Information</u>

## Index

accuracy grade, 181, 254	function-generating mechanisms with no
accuracy, of	undesirable structural redundancy, 99,
computation, 65, 68	101-102, 108, 111 (see also optimally
design procedure, 71	structured FGMs)
finite element analysis, 72, 149	chaotic vibrations' study, 116-117, 124
positioning, 89, 94 (see also accuracy of position	qualitative methods of detecting and measuring
control)	chaos, 117
solution, 60, 63	bifurcation diagrams, 120
activation of the mechanisms at near-zero	bifurcation maps, 121
frequencies, 167, 195	Fourier spectra, 121
agricultural machines,	Poincaré sections and maps, 118
harvester combines, 266, 269–270	time charts and phase trajectories, 117
algorithms, of	quantitative methods of detecting and measuring
air-damping control, 140, 185–188,	chaos, 122
225	Lyapunov exponents, 125, 141
position control, 189–192	fractal dimensions, 124
stiffness control, 25, 175, 181	stability conditions for mechanisms with
antifriction composites	negative/quasi-zero stiffness, of the
based on microplasma oxidation, 164	first type, 127–131
with perfluorine compounds, 163, 165	second type, 131–133
atlases, of	stable motion of active suspensions with the
bogie suspensions, 109, 111	RMs, 133–141
function-generating mechanisms, 106, 108,	clearances in kinematic pairs, 153-159
111	compactness of mechanisms with negative stiffness,
seat suspensions, 103, 106, 108	254
1	composite parametric elements with negative/
beam-shaped elastic structures	quasi-zero stiffness, 62, 210, 232, 285–291
bar systems, 29, 37	based on carbon fibers, 288–290
slender beams, 29, 36, 41	computer-aided test systems, 203, 221-224
bending moments, distribution, 68	vibration measuring equipment, 268
bending stiffness, 288	vibration simulating equipment
boundary conditions, 68, 75	electrodynamic exciters, 220–221
fixed, 46	electrohydraulic exciters, 220-221
hinged, 43–45	fatigue testing machines, 204, 210
movable end-support, 218	pneumo-mechanical vibrating tables and
buckling load, 27, 42, 75–77 (see also critical	platforms, 222
force)	construction equipment, 2
first or top, 47, 75	Caterpillar mini excavators, 272–273
second or bottom, 47, 75	wheel short-chassis cranes, 270–272
buckling problem, 37	control algorithms
	adaptive control of steady-state vibration motion,
candidates, for	188–191, 193 (see also invariant control)
parametric elements with negative stiffness in	stabilization of transient vibration motion,
large, 48–49, 53, 62	190–191, 193
	,



Index

295

control objects, 174	mechanisms with negative stiffness, 29, 78, 267,
control parameters	274, 278–283
acceleration, 4-6, 223-225	gears, 253, 257–258
air pressure, 175–181	duality of the mechanism performance, 75–77
damping, 185–188, 196	
relative position, 186–192, 196, 246, 249	effect, of
relative velocity, 189–192	magnetic levitation, 13–14
stiffness, 175–177, 181–185	negative stiffness, xvii, 25–28, 32, 41, 47, 68–70,
criteria, of	74–78, 126–136, 147, 168, 183–184, 205,
quality, 4, 25, 100–101, 227–228, 240–242,	211–213, 216–217, 245, 289–290
250	quasi-zero stiffness, 25, 28, 32, 41, 136, 169,
similarity, 281–282	217, 241, 289–290
stability, in	effective area, of
chaotic motion, 128–141	negative/quasi-zero stiffness control, 136, 140,
steady-state vibration motion, 5, 185, 191, 195,	168–169, 212–213
250	pneumatic control system inlet/outlet orifices,
transient vibration motion, 185–188, 251	180, 188, 191–193, 243–245
cross forces, distribution, 152–153	elastic limits, 67, 279
cross section of thin-walled structures, 60, 73, 163,	elastic responses, operating modes, 26–28, 33, 47,
286–288	75, 168–169, 182–183, 207, 215–217, 241, 245, 270, 282, 284, 287, 200 (**********************************
cylindrical bending of thin-walled structures, 53,	245, 279, 283–284, 287–290 (see also
60, 148, 286–288	force-displacement curves) elasticity theory, 57–61, 146
dampare (saa also dampina machanisms)	enumeration of a mechanism structure, 86, 91,
dampers ( <i>see also</i> damping mechanisms) external, fluid, 20, 103, 109, 135, 168, 195, 207,	95–97, 101–113
230, 242, 252, 278	ergonomics of seats, 267, 272, 274, 280
electro-rheological, 249–250	equations, of
magneto-rheological, 249–250	air balance, 178–181
damping	compatibility, 58–59
air, with variable structure, 185–188	equilibrium, 59, 148–149
critical, 139, 153, 160	state, 59
slip, minimization, 160, 164	vibration motion, 127–129, 140, 160, 178–179
structural, measuring and reducing, 146–148,	equilibrium
162–163, 212–213	stable, 132, 134–136, 138, 141
damping forces, variability, 20, 130, 177, 214, 251	unstable, 128-133, 138
deformation problem under postbuckling, 52–55	
(see also geometrically nonlinear	failures of mechanism performance, structural
deformation)	sources, 89–94
degree-of-freedom	fast Fourier Transform, 5 (see also FFT)
parametric, xvii, 95 (see also local mobility)	fatigue testing machines, 204, 210
structural, xviii, 1, 85, 95 (see also mobility)	finite element analysis, methods, 56, 149, 212, 287
design models	(see also FE-analysis)
generic, 40	finite element models (see also FEs)
numerical, 68–71, 132	basic, 62–65, 148, 152
design parameters of mechanisms with negative/	gap (see also additional FEs)
quasi-zero stiffness, 66-81, 212	node-to-line, 148–152
development test, features in	node-to-node, 148-152
dynamics, 14, 20, 230-232	force closure of mechanisms' kinematic chains,
statics, 205, 208-217, 287-291	209, 254, 267
the field, 10, 16, 268	form closure of mechanisms' kinematic chains, 209,
dimensioning of vibration protection mechanisms	254, 267
with negative/quasi-zero stiffness, 36–40,	fractal, 119
71, 77–81, 253–258	dimension, 124
dimensions, of	structure, 122–123
parametric elements with negative/quasi-zero	frequency ranges of vibration
stiffness, 28, 66, 71	infra, xvii, 1–4, 208, 225, 230, 232



## 296 Index

frequency ranges of vibration (cont.) low, xvii, 1–4, 225, 232, 273 middle, 1–4, 273	humans' safety and comfort providing by the vibration protection systems, in construction and field works, 270–273
near-zero, xvii, 195–196	flights, 273–275
frequency responses of transport vibration	ridings, 277–278
protection systems, 8–18, 124, 195, 225,	Hdings, 277 270
230, 232, 242, 252	idle degree-of-freedom, 184 (see also local DOF)
friction	infra-low-frequency vibrations most harmful and
Coulomb, 130, 160–161	gangrenous for humans and engineering,
rolling, 258	2–4, 7–15
sliding	infra-low-frequency vibration affecting humans
extremely small, 164–165, 168, 258–259	inside vehicles, 7–11, 16–18, 270–278
lubricated, 163–166	outside vehicles, 7, 8, 13
viscous, 251	instability of vibration motion
function-generating mechanisms	global, 40, 88
atlases, 97, 103, 106–109, 111	local, 40, 88–89
methods of the type and number synthesis/	invariance, of
analysis, 29–30, 86–89	design parameters, 88, 91, 281
fundamental design relations, 47–48, 71, 279	mechanism characteristics, 74–76, 95, 100, 156,
Tundamental design felations, 47–48, 71, 279	168, 190–191
gear ratio, 176, 208, 256	iterative procedures in solving the postbuckling
gearings, spatial, 105–107, 213, 254–256	problem, 54–57, 146
gears gears	problem, 54–57, 140
bevel, 108, 111, 167, 176, 253–255	joining the redundant mechanisms to vibration
mini-gears, 255–259 ( <i>see also</i> mini-trains), with	protection mechanisms, 87–89, 95, 106,
screw-nut mechanism, 182–183	111, 167–168, 209, 253–255
worm mechanism, 246–247	joints, movable, 85–87, 91 ( <i>see also</i> kinematic
	pairs)
generic properties of parametric elements with negative/quasi-zero stiffness, 53	• ,
generic models of parametric elements with	kinematic chains
negative/quasi-zero stiffness, 41, 49, 53	active, 91, 98 (see also active KC or KC with
geometrically nonlinear problem of postbuckling,	actuator)
52–55, 146	closed, 85
gravity parameters, 1, 38	main, 29–30, 85
	open, 85, 90–91
hardening, of	passive, 92 (see also passive KC)
gearings, 258–259	redundant, 29–30, 85, 98, 100
guiderails, 164–165, 258–259	kinematic pairs (see also movable joints)
slide bearings, 164–165, 258–259	active, 90, 93 (see also active KP)
harmony operation of mechanisms with positive and	higher
negative stiffness, 25, 252	centroid, 108, 111
health 7, 13–16, 275, 277 (see also hygienic)	lower
vibration standards, general and industrial	prismatic, 103, 105, 109, 111 (see also prism)
heavy damped suspensions as vibration amplifiers,	revolute, 97, 99, 103, 105, 108, 109,
8, 10–13, 20, 35, 208, 230, 232, 242,	111
248–252	spherical, 108, 109, 111
heavy trucks, inside actual vibrations and vibration	passive, 90, 97 (see also passive KP)
protection, 17-20, 276-277	kinematic structure
helicopters, inside actual vibrations and vibration	in-parallel, 90
protection, 14-17, 273-275	redundant, 26, 29, 97
Hermitian family polynomials, 63, 149	
holographic interferometry, 218–219	labeled graphs, 101-103, 106, 108-109, 111
human operators as objects of the infra-low	land vehicles, inside actual vibrations and vibration
vibration protection, xviii, 1-4, 101-103,	protection, 17-20, in
190–191, 195–196, 264–265,	electromotor buses, 276–277
269–278	heavy trucks, 18, 276



Index

297

models of stress-strain state of parametric elements linear thin-shell theory, key hypothesizes, 54, 58 with negative/quasi-zero stiffness, 55, 73–76, 287 link mechanisms with negative/quasi-zero stiffness, 29, 37, 88, 105, 108, 111, 267, 274, 280 nanopowders use, 164-165 local buckling, 27 near-zero frequency vibration motion, 160-162, 232 mobility, 35, 95, 103 (see also local DOF) negative stiffness, low-cycle loading/unloading of mechanisms with in rotation, 26, 30, 105, 108, 111, 128-129 negative/quasi-zero stiffness, 204-205, 210 in translation, 26-30, 88-89, 105, 108, 111 Lyapunov exponents, neutral largest, 125-126 axis, 42, 148 maps, 131, 134, 138 (see also chaotic diagrams) position, 33, 37, 191 node displacements, equations, 54-56, 63-65 Novozhilov, theory of the shells, 57-60 machines suspended, 275-278 number synthesis of a mechanism, 85, 91, 97, 101, unsuspended, 269-275 104-105, 108, 110-111 (see also man-machine systems, 1-4 enumeration of the mechanisms) Maxwell-Betti theorem, 59 mechanical Q-factor, 5, 96, 272 objects of transport infrastructure, 13-14, 281-283 mechanisms with negative/quasi-zero stiffness, overall dimensions of the vibration protection characteristics mechanisms with negative/quasi-zero force-displacement, 26-28, 33, 130, 133, 136, stiffness, 29-30, 78, 98, 209, 254, 267, 274, 280, 283-284, 290 140, 147, 151, 163, 168-169, 205, 211-213, 217, 245, 279-284, 287-290 (see also packaging of parametric elements with negative/ elastic response) geometrical, 36-40, 66, 77-81, 97, quasi-zero stiffness, 62, 73 278-282 parametric elements, load-bearing, kinematic, 66, 69-72, 212 selection of type, 181-182, 207-208, 238-242 phase portrait, 130, 133, 136 path-linearization, 77-78, 168, 183, 217, 290 trajectories of vibration motion, 118-119 payload capacity of vibration isolating mechanisms, 168, 207, 217 damping control critical, 153, 169 (see also at lock-up perfluorine compounds, multilayered and behavior) incompressible, 163-166 light, with variable structure, 138, 187, performance of vibration protection mechanisms with negative/quasi-zero stiffness slip 160, 164, 169 (see also sliding) degradation, sources and reasons, 33, 90-93 structural, 162-163, 212-213 duality, 75-77 motion control, 186-192 failures, 39, 89, 94 criteria, 185, 188, 196-197 inversion, 26-27, 140 features, 173 loss, sources and reasons, 94 methods, of sensitivity to parameter change, 71-76, 125, 211 adaptive control, 186-191 portrait, 130, 133, 136 stabilization, 187-189, 191-192 stability conditions, 133, 138-141 trajectory, 118-120 stiffness-displacement, 183 Poisson's ratio, 48, 59, 286, 288 Poincare sections and maps of a vibration motion, stiffness control, xvii, 25-27, 175-177, 183-185, 216-217, 243-245 118-120, 134, 139 minimization of positive stiffness, 181-185, potential energy of elastic deformation, 56-63, 146 216, 243 (see also quasi-zero stiffness) postbuckling structural conditions, 85 in large, 47, 53, 75-78, 105, 108, 111, 289 mechanisms with negative/quasi-zero stiffness, in small, 28, 33, 36-40, 76, 88-89, 105, 111, 289 precompressed parametric elements of the types link, 29, 88, 105, 111, 128 mechanisms with negative/quasi-zero cam, 30, 38-39, 89, 105 stiffness, 29-30, 41, 53, 128, 210 (see also electromagnetic, 14, 28, 30, 39-40 membrane forces, distribution, 58-60 prototypes of mechanisms with quasi-zero stiffness, microarc oxidation, 164-165, 257-259 14, 28-30, 73, 167, 209, 254, 280



## 298 Index

quality of vibration protection systems criteria, 4-6, springs with negative/quasi-zero stiffness, shapes 100, 227-228 air-bags, rodless, 28, 174, 242 absolute effectiveness, 227, 242, 250 bar systems, 29 crest factor, 5, 235, 250-251 elastic rods, 28 relative effectiveness, 195, 227-230 electromagnet sets, 14, 28, 30 transmissibility, 5, 167, 227, 230, 232, 250, 268 slender beams, 28, 29, 41 quasi-zero stiffness thin plate sets, 49, 53, 73 in rotation, 25-26, 30, 111 thin shallow shells, 53 in translation, 14, 25-30, 88-89, 108, 111, 128 sprung mass, 3, 160, 179 (see also suspended mass) stability of motion of mechanisms with negative/ railroad vibration protection systems with negative/ quasi-zero stiffness quasi-zero stiffness at nearly-zero frequencies, 133, 162 engineer seats, 30, 280 under minimal damping, 138, 141, 162, 185, 192 infrastructural objects, floating track bed static-geometric analogy, 60 elements, 284 steady-state vibration motion, 195, 225, 230, 232 rolling stock, regular, cars and locomotives, 29, stiffness control methods, 25-28, 41, 175, 243-245 111, 283 stiffness matrix, 56, 64, 146 rolling stock, high-speed, magley, 14, 111 strain energy, 56-61, 63, 146 redundant stress maximum in parametric elements with constrains, structural, 85-87, 95, 104, 105, 108, negative/quasi-zero stiffness, 48, 67-68, 110-111 (see also RCs) 74-76, 78, 150-151, 163, 279, 283-284, kinematic chains, xviii, 29-30, 85, 88-89, 98-99, 287 111 (see also RKCs) structural kinematic pairs, 85, 95, 103-105, 110-111 (see complexity, 102, 106, 108, 111 also redundant KPs) conditions of a mechanism, 85 mechanisms with negative stiffness, xviii, 96, damping, 146-147, 163, 212-213 105-106, 108, 111, 281-283 (see also RMs) elements, 86, 88-89, 103, 105-106, 108-109, 111 first type, in translation, 126-128 fixed, 29, 30, 103, 105, 108 second type, in rotation, 126-128 parametric elements, xviii, 96, 99, 101 input, 29, 30, 88-89, 103, 105, 108, 111 intermediate, 88-89, 103, 105, 108-109, 111 relative damping ratio, 5, 129, 138, 166, 203, 208, 217 movable, 29, 30 displacements, 187-189, 191-192, 246 output, 103, 105-106, 108-109, 111 velocities, 187-189, 192 real, 153-154 virtual, 153-154 resonance amplifiers, 20, 33, 35, 232, 242, 252 Reuleaux definition for coupling, 101 formulae, 91, 95, 103 (see also structural ride comfort conditions, 5, 9, 189, 192, 268, 277 equations) rigid loop, 112, 156 (see also motionless structure) identity, 100-101 rod-shaped structures with negative/quasi-zero invariance, 100, 156 stiffness, 29, 88-89, 105, 111, 128 numbers, 85, 91, 97, 101, 104-105, 108, 110-111 seat suspensions, type selection, 20, 103, 106, redundancy, xviii, 85, 96-97, 101, 104-106, 110 206-209, 267, 280 undesirable, 85, 95, 103 selection of accelerometers, 223, 247 synthesis, methods, 86, 93, 101 (see also sensitivity to the parameters change, 71-76, structural design) 212-213 suspension end-stops, 215-216, 249 shape function formulation, 43-47, 54, 60-61, 149 suspensions with negative/quasi-zero stiffness, for cabin mountings, 78 shear buckling, 28, 244-245 sign-changing stiffness, xvii, 25-28, 33, 47, 88-89 cargo containers, 78, 259 similarity criteria for mechanisms with negative measuring instrument platforms and tables, 29 stiffness, 281 railroad floating track bed elements, 14, 284 spring materials regular and high-speed railroad cars and nonmetal composites, 210, 287-288 locomotives, 14, 29, 111, 283 rubbers, 28, 241 seats for human operators, staff and passengers, of rubber-metals, 28-30, 241 caterpillar excavators, 78, 108, 209, 267 city buses, 78, 108, 209, 267 spring steels, 29, 163, 210, 219, 241, 287

wire ropes, 29

harvester combines, 78, 108, 209, 267



Index

299

heavy trucks, 78, 108, 209, 267 transfer functions, 25, 121, 176, 194, 213, 280-281 helicopters, 108, 209, 267 transverse-longitudinal bending of parametric railroad cars and locomotives, 30, 78, 108, elements with negative/quasi-zero 209, 267, 280 stiffness, 41 wheel cranes, 78, 108, 209, 267 type diagrams of mechanisms, 29-30, 88-90, 97, vehicle bodies, 78 (see also chassis) 103, 105, 108-109, 111, 284 suspension parametric control, methods active, 14, 167, 184, 193, 209, 222, 267 undamped systems, 5 (see also undamped VPS) passive, 28-30, 209, 267, 274, 280 unsprung mass, 3 (see also unsuspended parts) semiactive, 249 unsuspended vehicles, 77, 269 suspensions softening, other methods urban electric buses, 276-278 (see also trolley direct, 242-245 buses) with no elastic elements, 245-248 variable air-damping, 138, 177, 187, 192, 196, suspensions, types combined, 11, 109, 111 (see also hybrid) electromagnetic, 14, 30 vibration dose value, 6 mechanical, 29-30, 111, 209, 267, 274, 280, 284 vibration excitation, computer-aided equipment pneumatic, 106, 167, 209, 222, 242, 267 electrodynamic exciters, 221-222 (see also EDEs) synthesis of mechanisms electrohydraulic exciters, 221–222 (see also EHEs) geometrical, 66-67, 71, 77 (see also pneumo-mechanical exciters, 222 dimensioning) vibration exposure time, 6 dynamic, 97, 129, 140, 160-162, 178-180 vibration limits, 7-13, 16, 33, 275-277 vibration measured parameters kinematic, 154-159, 282 number, 91, 97, 101, 105, 108, 111 relative accelerations, 225 type, 29-30, 86-89, 97, 105-106, 108, 111, 209 relative displacements, 187-192, 246 relative velocities, 187-189, 192 tensor equations, 57-60 vibration measurement systems automotive, one/two-channel, 268 test conditions city streets and motor company testing areas, 275 stationary, multi-channel, 268 construction works, 270-272 vibration motion, types farm operations, 269 chaotic, 116-118, 124 (see also chaotic vibration) helicopter flights, 273-274 deterministic, 118, 124 lab development, 208, 216, 218, 228 vibration protection mechanisms, with negative/ test equipment quasi-zero stiffness general-purpose, 203-204, 210, 221, 268 (see selection of type, 104-106, 126-128 also standard) vibration protection, methods nonstandard, 164, 210, 221-222, 268 external heavy damping, 248-252 structural damping, 146-147, 163, 212, 217 thickness of thin-walled structures postbuckled, 48, 59, 66, 73, 149, 288 vibration absorbing, 15-17, 242 thin-walled elastic structures under postbuckling vibration isolation, xviii, 21 approximation method, 54-55 fundamental design relations, 48, 71, 279 working travel with negative/quasi-zero stiffness effective, 27-28, 33, 40, 168, 184, 212-213, 287, generic models thin plates, 49, 53, 62-65, 73, 128, 148, 286 290 (see also effective area) packaging, 49, 62, 73, 148 total, 26-28, 33, 47, 68, 74-78, 130, 133, 136, lamination, 62, 73, 128 140, 147, 151, 163, 168, 183, 184, 211-213, shallow cylindrical shells, 48, 53 217, 245, 279, 283, 284, 287, 289, 290 shallow spherical shells, 53

time history, 118, 225

Young's modulus, 48, 59, 149, 286-288