

Introduction to Graph Signal Processing

An intuitive and accessible text explaining the fundamentals and applications of graph signal processing. Requiring only an elementary understanding of linear algebra, it covers both basic and advanced topics, including node domain processing, graph signal frequency, sampling, and graph signal representations, as well as how to choose a graph. Understand the basic insights behind key concepts and learn how graphs can be associated with a range of specific applications across physical, biological, and social networks, distributed sensor networks, image and video processing, and machine learning. With numerous exercises and Matlab examples to help the reader put knowledge into practice, and a solutions manual available online for instructors, this unique text is essential reading for graduate and senior undergraduate students taking courses on graph signal processing, signal processing, information processing, and data analysis, as well as researchers and industry professionals.

Antonio Ortega is a professor of electrical and computer engineering at the University of Southern California, and a fellow of the IEEE.





Introduction to Graph Signal Processing

ANTONIO ORTEGA

University of Southern California





CAMBRIDGE UNIVERSITY PRESS

University Printing House, Cambridge CB2 8BS, United Kingdom

One Liberty Plaza, 20th Floor, New York, NY 10006, USA

477 Williamstown Road, Port Melbourne, VIC 3207, Australia

314–321, 3rd Floor, Plot 3, Splendor Forum, Jasola District Centre, New Delhi – 110025, India

103 Penang Road, #05-06/07, Visioncrest Commercial, Singapore 238467

Cambridge University Press is part of the University of Cambridge.

It furthers the University's mission by disseminating knowledge in the pursuit of education, learning, and research at the highest international levels of excellence.

www.cambridge.org

Information on this title: www.cambridge.org/9781108428132

DOI: 10.1017/9781108552349

© Antonio Ortega 2022

This publication is in copyright. Subject to statutory exception and to the provisions of relevant collective licensing agreements, no reproduction of any part may take place without the written permission of Cambridge University Press.

First published 2022

A catalogue record for this publication is available from the British Library.

Library of Congress Cataloging-in-Publication Data

Names: Ortega, Antonio, 1965- author.

Title: Introduction to graph signal processing / Antonio Ortega, University of Southern California.

Description: New York, NY: Cambridge University Press, 2021.

Includes bibliographical references and index.

 $Identifiers: LCCN\ 2021038900\ |\ ISBN\ 9781108428132\ (hardback)$

Subjects: LCSH: Signal processing. \mid BISAC: TECHNOLOGY & ENGINEERING /

Signals & Signal Processing | TECHNOLOGY & ENGINEERING / Signals & Signal Processing

Classification: LCC TK5102.9 .O77 2021 | DDC 621.382/2-dc23

LC record available at https://lccn.loc.gov/2021038900

ISBN 978-1-108-42813-2 Hardback

Cambridge University Press has no responsibility for the persistence or accuracy of URLs for external or third-party internet websites referred to in this publication and does not guarantee that any content on such websites is, or will remain, accurate or appropriate.



To Mineyo and Naoto





Contents

Preface Acknowledgments				page xiii xv	
			nents		
	Nota	tion		xviii	
1	Intro	duction		1	
	1.1	From S	Signals to Graph Signals	1	
		1.1.1	Graphs	1	
		1.1.2	Frequency Analysis of Graph Signals	4	
		1.1.3	Filtering and Sampling Graph Signals	8	
		1.1.4	Graph Signal Processing versus Vector Processing	9	
	1.2	GSP T	Cools Adapt to Graph Characteristics	10	
		1.2.1	Selecting the Right Graph for a Task	10	
		1.2.2	Graph Diversity: How General Are GSP Tools?	10	
	1.3	Graphs	s in Classical Signal Processing	11	
		1.3.1	Path Graphs, Cycle Graphs and Discrete-Time Signals	11	
		1.3.2	Images and Grid Graphs	14	
		1.3.3	Path and Grid Graphs with Unequal Weights	14	
	1.4	Graphs	s Everywhere?	15	
		1.4.1	Physical Networks	15	
		1.4.2	Information Networks	17	
		1.4.3	Machine Learning	18	
		1.4.4	Analyzing Complex Systems	19	
		1.4.5	Social Networks	20	
	1.5	Mathe	matical Models of Graphs	21	
	1.6	Roadn	nap and Approach	24	
2	Node	Domain	Processing	29	
	2.1	Basic l	Definitions	29	
	2.2	Locali	ty	33	
		2.2.1	Importance of Locality	34	
		2.2.2	What Do We Mean by Local Graph Processing?	34	
		2.2.3	Node-Centric Local Processing	36	
		2.2.4	Clustering and Graph Cuts	37	
		2.2.5	Graph Coloring	38	



viii Contents

	2.3	Algabraia Parragantations of Graphs	41
	2.3	Algebraic Representations of Graphs 2.3.1 Adjacency, Incidence and Degree Matrices	41
		• •	46
		<u> </u>	49
	2.4	1 1	
	2.4	Node Domain Graph Filters	51
		2.4.1 Simple One-Hop Filters and Their Interpretation	51
	2.5	2.4.2 Polynomials of One-Hop Operators	53
	2.5	Graph Operators and Invariant Subspaces	56
		2.5.1 Minimal Polynomial of a Vector	56
		2.5.2 Eigenvectors and Eigenvalues	58
		2.5.3 Minimal Polynomial of Z and Invariant Subspaces	60
		2.5.4 Algebraic and Geometric Multiplicities and Minimal Polyno-	<i>C</i> 1
		mials	64
		2.5.5 Practical Implications for Graph Filter Design	69
3	Grapi	h Signal Frequency – Spectral Graph Theory	75
	3.1	Graph Fourier Transforms (GFTs)	76
		3.1.1 From Invariant Subspaces to Graph Signal Representations	76
		3.1.2 Diagonalizable Z	77
		3.1.3 Defective Z	78
		3.1.4 How Many GFTs Are There?	78
	3.2	Graph Signal Variation and Z Quadratic Forms	79
		3.2.1 Combinatorial Laplacian	79
		3.2.2 Self-Loops and Variation	81
		3.2.3 GFTs and Variation	82
		3.2.4 Symmetric Normalized Laplacian	85
		3.2.5 Variation Based on Adjacency Matrices	85
		3.2.6 GFT Visualization	86
	3.3	Graph Filtering – Frequency Domain	89
		3.3.1 Frequency Domain Representation of Polynomial Filters	89
		3.3.2 Node and Frequency Domain Filtering Implementations	90
		3.3.3 Interpretations of \mathbf{Z}^k	94
		3.3.4 Graph Filters, Graph Signals and Convolutions	95
	3.4	GFTs of Common Graph Operators	96
		3.4.1 Adjacency Matrix	96
		3.4.2 Graph Laplacians of Undirected Graphs	97
		3.4.3 Normalized Adjacency Matrices and Random Walk Laplacian	99
		3.4.4 Doubly Stochastic Normalization	100
		3.4.5 Irregularity, Normalization and the Choice of Inner Product	101
	3.5	Graph Structure and Graph Spectra	104
		3.5.1 Spanning Trees and the Matrix Tree Theorem	104
		3.5.2 Topology and Eigenvalue Multiplicity	105
		3.5.3 Bipartite Graphs	108
		3.5.4 Bounds on Eigenvalues	109



			Contents	ix	
		3.5.5	Nodal Domain Theorems	113	
4	Samı	pling		120	
	4.1	Graph	Signal Models	120	
		4.1.1	Challenges in Graph Signal Model Selection	120	
		4.1.2	Bandlimited and Approximately Bandlimited Signals	121	
		4.1.3	Piecewise Smooth Signals	123	
		4.1.4	Statistical Models	125	
		4.1.5	Graph Signal Stationarity	127	
	4.2	_	ing Constraints	131	
		4.2.1	Total Number of Samples	131	
		4.2.2	Distributed Systems	131	
		4.2.3	Diffusion and Sampling	132	
	4.3		m Formulation	132	
		4.3.1	Node Domain Sampling	132	
		4.3.2	Frequency Domain Sampling	133	
		4.3.3	General Conditions for Reconstruction	134	
		4.3.4 4.3.5	Reconstruction of Bandlimited Signals	135	
	4.4		Alternative Reconstruction Algorithms ing-Set-Optimization Algorithms	136 138	
	4.4	4.4.1	Sampling of Noise-Free Data	138	
		4.4.2	Criteria for Robust Sampling	139	
		4.4.3	Robust Spectral Sampling	140	
		4.4.4	Random Sampling	143	
		4.4.5	Sampling Based on Localized Operators	144	
	4.5		arisons and Insights	145	
5	Grap	h Signal	Representations	149	
	5.1	-	Frequency Localization and Uncertainty Principles	149	
		5.1.1	Measuring Localization for Graph Signals	151	
		5.1.2	Compact Support in the Node and Frequency Domains	154	
		5.1.3	Graph Slepians	155	
	5.2	Repres	senting Graph Signals: Goals	155	
		5.2.1	Structured Dictionaries	156	
		5.2.2	Exact Reconstruction	156	
		5.2.3	Orthogonality	157	
		5.2.4	Critical Sampling and Overcomplete Representations	157	
		5.2.5	Localization	157	
		5.2.6	Graph Types Supported, Graph Approximation and Simplifi-	158	
	<i>7</i> 2	cation			
	5.3		ng a Simple Representation Based on One-Hop Operations	158	
	5.4		Domain Graph Signal Representations	160	
		5.4.1	Node Domain Graph Wavelet Transforms (NGWTs)	160	
		5.4.2	Graph Lifting Transforms	162	



Contents

		5.4.3	Subgraph Filterbanks	164
	5.5	Freque	ncy (Spectral) Domain Graph Signal Representations	165
		5.5.1	Spectral Graph Wavelet Transforms (SGWTs)	165
		5.5.2	Chebyshev Polynomial Implementation	167
	5.6	Critica	lly Sampled Graph Filterbanks	169
		5.6.1	Downsampling-Upsampling Operations for Graph Signals	171
		5.6.2	Bipartite Graphs	171
		5.6.3	Ideal Filterbank Design	172
		5.6.4	Graph Filterbanks	174
		5.6.5	Pyramid Transforms	177
	5.7	Diffusi	on Wavelets	178
6	How 1	to Choos	e a Graph	181
	6.1	Graph	Approximation	182
		6.1.1	Edge Removal and Graph Spectrum	183
		6.1.2	Graph Sparsification	185
		6.1.3	Graph Simplification and Graph Fourier Transform Computation	187
		6.1.4	Topology Selection	188
		6.1.5	Graph Reduction	190
	6.2	Constr	ucting Graphs from Node Similarity	192
		6.2.1	Computing Graph Weights as a Function of Similarity	192
		6.2.2	Similarity Graph Optimization	193
	6.3	Learnii	ng Graphs from Signals	194
		6.3.1	Basic Principles and Intuition: Empirical Covariance	195
		6.3.2	Learning Unrestricted Operators from Data	196
		6.3.3	Node Domain Techniques	197
		6.3.4	Frequency Domain Methods	200
		6.3.5	Discussion	200
7	Appli	cations		202
	7.1	Overvi	ew, Application Domains and Methodology	202
		7.1.1	Application Domains	203
		7.1.2	An Application Checklist	204
	7.2	Physical	al, Biological and Social Networks	205
		7.2.1	Transportation Networks: Road Networks	205
		7.2.2	Infrastructure Networks	206
		7.2.3	Brain Networks	206
		7.2.4	Social Networks	207
	7.3	Distrib	uted Sensor Networks	208
		7.3.1	Data Transport	208
		7.3.2	Sensor Data Analysis	210
	7.4	Image	and Video Processing	211
		7.4.1	Transforms on Regular Grid Graphs	211
		7.4.2	Graph Selection	215



		Contents	ΧI
	7.4.3	Filtering	217
	7.4.4	Graph-Based Image and Video Compression	218
	7.4.5	Image Restoration	222
	7.4.6	Image Segmentation	224
7.5	Machin	ne Learning	224
	7.5.1	Graphs and Graph Signals in Learning Applications	224
	7.5.2	Unsupervised Learning and Clustering	227
	7.5.3	Semi-supervised Learning	229
	7.5.4	Graph Convolutional Neural Networks	230
Appendix A	Linear Al	gebra and Signal Representations	235
A.1	Signal	Spaces and Subspaces	235
A.2	Bases		236
	A.2.1	Span	236
	A.2.2	Linear Independence	237
	A.2.3	Bases	238
A.3	Inner F	Product, Distance and Similarity	239
	A.3.1	Definitions	239
	A.3.2	Interpretation: Signal Similarity	240
A.4	Orthog	onal and Biorthogonal Bases	242
	A.4.1	Biorthogonal Bases	242
	A.4.2	Orthogonal Bases	243
	A.4.3	Least Squares Approximation	243
	A.4.4	Gram-Schmidt Orthogonalization	245
A.5	Diction	naries and Overcomplete Representations	245
	A.5.1	Signal Representations Are Not Unique	246
	A.5.2	Minimum ℓ_2 Norm Representation	246
	A.5.3	Matching Pursuits and Orthogonal Matching Pursuits	248
Appendix B		Matlab: The GraSP Toolbox	253
	•	n Girault	
B.1	_	Up Matlab	253
B.2	-	er 1 Use Cases	254
	B.2.1	Generate a Random Graph: Watts-Strogatz Model	254
	B.2.2	Additional Random Graphs: Classical Models	255
	B.2.3	Additional Random Graphs: Sensor Network (Geometric Graph)	256
	B.2.4	Some Non-random Graphs	258
	B.2.5	Plotting a Graph Signal on a Path Graph	259
	B.2.6	Importing a Graph	259
	B.2.7	Building a Graph from Scratch	261
B.3	_	er 2 Use Cases	262
	B.3.0	The Random Walk Laplacian	262
	B.3.1	Linear Graph Filter	263
	B.3.2	Polynomial Graph Filter	263



xii Contents

B.4	Chapter 3 Use Cases		
	B.4.1	Graph Fourier Transform Computation and Visualization	265
	B.4.2	Kernelized Filter	266
	B.4.3	Convolutive Filter	267
	B.4.4	Polynomial Filter (Approximation)	268
	B.4.5	Chebyshev Polynomial Filter (Approximation)	269
B.5	Chapte	r 4 Use Cases	270
	B.5.1	Node Sampling	270
B.6	Chapte	r 5 Use Cases	273
	B.6.1	Extended Application: SGWT with the Random Walk Laplacian	273
B.7	Chapte	r 6 Use Cases	277
	B.7.1	Graph Learning	277
B.8	Reference for grasp_show_graph Parameters 2		
B.9	Referen	nce for grasp_show_transform Parameters	282
Refere	ences		286
Index			297



Preface

This book grew out of my own research with students and collaborators, and evolved into a set of notes developed for a special topics course on graph signal processing at the University of Southern California. I have taught several versions of this material as a standalone class as well as in combination with advanced topics in signal processing (wavelets and extensions, dictionary representations and compressed sensing). In the meantime, much has changed since the first time I offered this class in Fall 2013. Graph signal processing (GSP) has grown as a field, understanding of specific problems has improved, and more applications have been considered. Both my experience in teaching this material and the evolution of the field informed the choices I made in writing this book.

First, while this is a book about graph signal processing, my goal has been to make the book accessible to readers who do not have any signal processing background. The main assumption I make is that readers will have taken an elementary linear algebra course. Appendix A provides a review of elementary concepts, presented from a signal representation perspective, and can be used to review this material.

Second, from my experience teaching this material to masters and PhD students, and from feedback I received from undergraduates who read early drafts of the book, I think the main challenge for those studying this topic for the first time is to understand the basic insights that make it possible to *use* the concepts. Without those insights, even if the mathematical ideas are understood, it is difficult to apply them. For this reason, I have spent time trying to develop intuition about the key concepts, lingering on ideas that are likely to be obvious to active researchers but hoping that they will prove to be useful to those new to the area. In short, whether or not I have succeeded in these goals, the word "Introduction" certainly deserves its place on the title.

Finally, by design, this book does not aim to provide a comprehensive and detailed survey of all recent research. In a rapidly evolving field this is difficult to do: much has been published but competing methods have not been compared, connections have not been made, the dust hasn't quite settled yet. I have chosen to summarize, classify and make connections where possible, but many details and approaches are left out. For advanced topics covered in this book (sampling, graph learning, signal representations) there are recent overview papers that provide a more detailed literature survey. Similarly, GSP is being used in a growing number of applications, and only a small subset of those are introduced in this book.



xiv **Preface**

How to use this book There are of course many different ways to use the material in this book for teaching. I describe some possible scenarios.

- For a semester-long advanced undergraduate class, Chapter 1 can be followed by the first three sections of Appendix A, and then the rest of the chapters. The remaining sections in Appendix A can be introduced before tackling Chapter 5. Additional programming assignments can be included to help students with limited Matlab experience.
- I have used this material as part of a semester-long graduate level class covering other topics (e.g., filterbanks, various types of wavelets and compressed sensing) and colleagues at other universities have used it in a similar way. For this type of course, the material in Appendix A can be used as an introduction to both GSP and to other advanced signal processing topics.
- Finally, a semester-long GSP class for advanced graduate students can complement
 the material in this book with reading from recent literature and advanced research
 oriented projects.

Exercises Since Chapters 1–3 and the two appendices cover basic concepts they contain exercises, while for Chapters 4–7, which deal with more advanced topics, students could be asked to read some of the published literature and work on a class project.

Matlab examples There are sections in Appendix B corresponding to Chapters 1–6, so this appendix can be used to complement each of those chapters, allowing students to get a more hands-on experience through Matlab code examples. Alternatively, Appendix B can be used as a standalone introduction to GraSP.

The GraSP toolbox is freely available at https://www.grasp-toolbox.org/. The source code for all examples and supplementary materials is available on the book's web page (http://www.graph-signal-processing-book.org/).



Acknowledgments

Interest in graph signal processing (GSP) has grown out of research on multiple applications where observed signals can be associated with an underlying graph. The journey that led me to completing this book started, more than 10 years ago, with the study of the representation and compression of signals captured by sensor networks. I often get asked about good applications for GSP, as if the results in this field had emerged out of purely theoretical research. In fact, much of what is described here, and in particular most of my own work on this topic, has been motivated by practical applications of GSP. While applications are important as a motivation, the reader should not be looking here for detailed solutions to problems that arise in specific applications. Instead, the main goal of this book is to develop the mathematical tools and insights that can allow us to think about some of these problems in terms of the processing of signals on graphs.

This book would not have been possible without the help and support of many people. First and foremost I would like to thank all of my current and former PhD students and postdoctoral fellows at the University of Southern California (USC). A brief note in these acknowledgments can hardly do justice to the importance of their contributions. Among my former PhD students I would like to thank in particular Alexandre Ciancio and Godwin Shen, who focused on transforms for sensor networks and developed methods for transforms over trees; Sunil Narang, who extended these ideas to graphs and introduced critically sampled graph filterbanks; Wooshik Kim, Yung-Hsuan (Jessie) Chao, Hilmi Egilmez and Eduardo Pavez, who developed new graph constructions and studied a number of image and video applications; Jiun-Yu (Joanne) Kao and Amin Rezapour, who took GSP methods into new and interesting application domains; and Akshay Gadde and Aamir Anis, who developed new methods for graph signal sampling and its application to machine learning. Ongoing and recent work with some of my current students, including Pratyusha Das, Keng-Shih Lu, Ajinkya Jayawant and Sarath Shekkizhar, as well as other work with Shay Deutsch, Alexander Serrano, Yoon Hak Kim, Lingyan Sheng, Sungwon Lee and Yongzhe Wang, also contributed to my research in this area. Finally, I would like to acknowledge the contributions of undergraduate and graduate students from various universities who visited USC and collaborated with my group, and in particular Eduardo Martínez-Enríquez from Universidad Carlos III, Madrid, and a series of students from Universitat Politècnica de Catalunya, Barcelona, and in particular Xavier Perez-Trufero, Apostol Gjika, Eduard Sanou, Javier Maroto, Victor González and Jùlia Barrufet, as well as David Bonet, who also provided comments on the manuscript.



χVİ

Cambridge University Press & Assessment 978-1-108-42813-2 — Introduction to Graph Signal Processing Antonio Ortega Frontmatter More Information

Acknowledgments

Special thanks go to Benjamin Girault. Benjamin started the development of the GraSP Matlab toolbox during his PhD studies and has continued to grow, develop, and maintain it since joining USC as a postdoc. Without Benjamin's contribution, including Appendix B, a comprehensive introduction to GraSP, and numerous code examples, this book would be a lot less useful to students and practitioners. Benjamin's contributions go far beyond this one chapter. He has been a close collaborator, his ideas have fundamentally shaped several parts of this book and he has also read multiple chapter drafts, some of them more than once, and sometimes early versions that were far from being ready. His comments on various versions of the manuscript were thoughtful and detailed, and always prompted me to go deeper into the material.

Throughout my time at USC I have been fortunate to work with many outstanding colleagues in the school of engineering and beyond. Among those who have collaborated more directly in research related to this book, I would like to mention Salman Avistimehr, Bhaskar Krishnamachari, Urbashi (Ubli) Mitra, Shrikanth (Shri) Narayanan and Cyrus Shahabi, as well as some of their students and postdocs, among others Sundeep Pattem, Mahesh Sathiamoorthy, Eyal En Gad, Aly El Gamal, Basak Guler, Nicolò Michelusi and Marco Levorato.

One of the great pleasures of academic research is having the opportunity to collaborate with researchers around the world, both remotely and through some very enjoyable visits. Some of these collaborations have had a major role in shaping my research in this area. During several visits to École polytechnique fédérale de Lausanne (EPFL), discussions with Pascal Frossard, Pierre Vandergheynst and David Shuman led to an overview paper and to additional collaboration with Thomas Maugey, Xiaowen Dong and Dorina Thanou, among others. It was during an extended sabbatical visit to National Institute of Informatics (NII) in Tokyo, Japan, that I started drafting this book, and I would like to thank my long-time collaborator Gene Cheung (then at NII, now at York University), and his students Wei Xu, Jiahao Pang and Jin Zeng for many productive discussions and a very fruitful collaboration. A short visit to the University of New South Wales (UNSW) in Sydney, Australia, and many discussions with David Taubman are also acknowledged. Since 2015 I have also visited regularly the Tokyo University of Agriculture and Technology (TUAT), and various parts of the manuscript were developed there. I am very grateful to TUAT and my hosts Yuichi Tanaka and Toshihisa Tanaka and their students, in particular Akie Sakiyama and Koki Yamada, for hosting me and for their collaboration. While most of this collaboration has been remote, I would also like to thank Vincent Gripon, and his students Carlos Lassance and Myriam Bontonou, at Institut Mines-Télécom (IMT) Atlantique and David Tay at Deakin University for their collaboration.

My work in this area has benefited greatly from collaboration and funding from several companies, and in particular I would like to thank Anthony Vetro, Dong Tian and Hassan Mansour at Mitsubishi Electric Research Labs (MERL), Phil Chou, Debargha Mukherjee, Yue Chen at Google and Amir Said at Qualcomm.

My research in this area has been supported by multiple sources over the years and this funding is most gratefully acknowledged. In particular, I would like to acknowledge multiple grants from the National Science Foundation and funding from the National



Acknowledgments

xvii

Aeronautics and Space Administration (NASA), from the Defense Advanced Research Project Agency (DARPA) and several companies, including Samsung, LG Electronics, Google, Mitsubishi Electric, Qualcomm, Tencent and KDDI. My summer and sabbatical visits were funded by the Japan Society for the Promotion of Science, NII, UNSW, TUAT and EPFL.

A first version of this manuscript was based on class notes for a special topics course on GSP at USC, and portions of successive drafts were used in teaching a class that included GSP along with wavelets. I am thankful to students in those classes for their questions and comments. Several students who took my undergraduate linear algebra class gamely volunteered to test my hypothesis that this material could be made accessible to undergraduate students with only basic linear algebra. Time will tell whether this is possible, or a good idea, but I am grateful to them, in particular Alex Vilesov, Reshma Kopparapu, Pengfei Chang, Lorand Cheng and Keshav Sriram, for their comments and questions and Catherine (Cami) Amein for her comments and for her wonderful cover illustration.

Several people helped me with detailed comments on various parts of the manuscript. In addition to Benjamin Girault, I would like to thank Yuichi Tanaka, David Tay, Hilmi Egilmez and Eduardo Pavez. Baltasar Beferull-Lozano and Gene Cheung both used the material in their teaching and provided comments. I am also thankful to the team at Cambridge University Press, including Julie Lancashire, Julia Ford, and Sarah Strange, for their inexhaustible patience and their support throughout the years it took for this book to be completed, Susan Parkinson for her detailed reading and many helpful suggestions and Sam Fearnley for managing the final production.

As of the time of this writing, 2020 and 2021 have been often described as "interesting" and "unusual" years. While not much else has gone according to plan in the last year, I can at least look at this book as a small (if late) positive outcome. I thank my wife Mineyo and our son Naoto for supporting me as I completed this project over the last few years, for pretending to believe my repeated (and highly unreliable) claims that the book was almost done and for making this year of work from home interesting and unusual, but in a very good way.



Notation

Vectors are written in boldface lowercase, \mathbf{x} , while matrices are in capital boldface, \mathbf{A} , \mathbf{B} . For graph matrices we use calligraphic letters if the matrix is normalized, so for example we would write \mathcal{L} instead of \mathbf{L} . A summary of other specific notation is given below.

$S_1 \cap S_2$	Intersection of sets S_1 and S_2
$S_1 \cup S_2$	Union of sets S_1 and S_2
S	Number of elements in set <i>S</i>
I	Identity matrix
J	Exchange matrix – all ones on the anti-diagonal
1	Vector with all entries equal to 1
A	Adjacency matrix
В	Incidence matrix
E	Matrix of self-loop weights
L	Combinatorial graph Laplacian
$\mathcal A$	Symmetric normalized adjacency matrix
\mathcal{L}	Symmetric normalized Laplacian
Q	Row normalized adjacency matrix
$\mathcal P$	Column normalized adjacency matrix
${\mathcal T}$	Random walk Laplacian
S	Sample covariance matrix
Q	Precision matrix
$i \sim j$	Nodes i and j are connected
I(A)	Indicator function (1 if <i>A</i> is true, 0 otherwise)
\mathbf{Z}	Generic one-hop fundamental graph operator
$\Delta_{\mathbf{S}}(\mathbf{x}) = \mathbf{x}^{T} \mathbf{S} \mathbf{x}$	Variation operator
$\mathcal{N}(i)$	Set of nodes connected to node <i>i</i>
$\mathcal{N}_k(i)$	Set of nodes in the k -hop neighborhood of node i
$p_{\min}(\mathbf{Z})$	Minimal polynomial of Z
$p_{\rm c}({f Z})$	Characteristic polynomial of Z
$p_x(\mathbf{Z})$	Minimal polynomial of Z for vector x
	-