

## Contents

<i>Preface</i>	<i>page</i> xi
<i>Acknowledgements</i>	xvii
1 Neural Networks: A Control Approach	1
1.1 Neural Networks: A General Presentation	4
1.2 Examples of Neural Networks	8
1.3 Rosenblatt's Perceptron and the Perceptron Algorithm	13
1.4 Multilayer Neural Networks	15
1.5 Adaptive Systems	18
2 Pseudoinverses and Tensor Products	23
2.1 Pseudoinverses	24
2.2 The Heavy Algorithm Theorem	32
2.3 Duals of Spaces of Linear Operators	34
2.4 Tensor Products of Linear Operators	36
2.5 Pseudoinverses of Tensor Products	38
3 Associative Memories	44
3.1 Optimal Synaptic Matrices of Associative Memories	44
3.2 The Heavy Learning Algorithm for Neural Networks	49
3.3 Multilayer Associative Memories	51
3.4 Continuous-Layer Associative Memories	54
3.5 Associative Memories with Gates	56
4 The Gradient Method	61
4.1 Extended Functions and Their Epigraphs	63
4.2 Convex Functions	64
4.3 Subgradient Algorithm	66
4.4 Support Functions and Conjugate Functions	68
4.5 The Minover Algorithm	73

viii	<i>Contents</i>	
5	Nonlinear Neural Networks	75
	5.1 Gradient Learning Rules	79
	5.2 Back-Propagation Algorithm	82
	5.3 Continuous Back-Propagation Algorithm	88
	5.4 Newton-type Methods	93
6	External Learning Algorithm for Feedback Controls	100
	6.1 Construction of the External Learning Algorithm	102
	6.2 Simulation Results: The Cart Pole	105
	6.3 Simulation Results: A Target Problem	109
	6.4 Uniform External Algorithm	113
7	Internal Learning Algorithm for Feedback Controls	118
	7.1 Viability Theory at a Glance	119
	7.2 Regulation of Control Systems	125
	7.3 Internal Learning Algorithm	133
	7.4 Stabilization Problems	137
8	Learning Processes of Cognitive Systems	139
	8.1 Viable Learning Processes	143
	8.2 Motivations and Comments	153
	8.3 Recognition Mechanisms	158
9	Qualitative Analysis of Static Problems	160
	9.1 Qualitative Frames	164
	9.2 Qualitative Equations and Inclusions	167
	9.3 Qualitative Operations	171
	9.4 Qualitative Solutions to Linear Problems	175
	9.5 The Constrained Inverse-Function Theorem	179
	9.6 Single-valued Nonlinear Equations	180
	9.7 Set-valued Problems	183
10	Dynamical Qualitative Simulation	187
	10.1 Monotonic Cells	189
	10.2 Transitions between Qualitative Cells	192
	10.3 Qualitative Equilibrium and Repeller	195
	10.4 The QSIM Algorithm	196
	10.5 Replicator Systems	198
	10.6 Qualitative Simulation of Replicator Systems	203
	10.7 Nonemptiness and Singularity of Qualitative Cells	207
	10.8 General Qualitative Cells	209
	10.9 Sufficient Conditions for Chaos	217
	<i>Appendix 1</i> Convex and Nonsmooth Analysis	219

<i>Contents</i>		ix
<i>Appendix 2</i>	Control of an AUV	252
	<i>Bibliography</i>	262
	<i>Index</i>	280