

Optimization Models

Emphasizing practical understanding over the technicalities of specific algorithms, this elegant textbook is an accessible introduction to the field of optimization, focusing on powerful and reliable convex optimization techniques. Students and practitioners will learn how to recognize, simplify, model and solve optimization problems – and apply these basic principles to their own projects.

A clear and self-contained introduction to linear algebra, accompanied by relevant real-world examples, demonstrates core mathematical concepts in a way that is easy to follow, and helps students to understand their practical relevance.

Requiring only a basic understanding of geometry, calculus, probability and statistics, and striking a careful balance between accessibility and mathematical rigor, it enables students to quickly understand the material, without being overwhelmed by complex mathematics.

Accompanied by numerous end-of-chapter problems, an online solutions manual for instructors, and examples from a diverse range of fields including engineering, data science, economics, finance, and management, this is the perfect introduction to optimization for both undergraduate and graduate students.

Giuseppe C. Calafiore is an Associate Professor at Dipartimento di Automatica e Informatica, Politecnico di Torino, and a Research Fellow of the Institute of Electronics, Computer and Telecommunication Engineering, National Research Council of Italy.

Laurent El Ghaoui is a Professor in the Department of Electrical Engineering and Computer Science, and the Department of Industrial Engineering and Operations Research, at the University of California, Berkeley.





Optimization Models

Giuseppe C. Calafiore

Politecnico di Torino

Laurent El Ghaoui

University of California, Berkeley





CAMBRIDGE UNIVERSITY PRESS

University Printing House, Cambridge CB2 8BS, United Kingdom

Cambridge University Press is part of the University of Cambridge.

It furthers the University's mission by disseminating knowledge in the pursuit of education, learning and research at the highest international levels of excellence.

www.cambridge.org Information on this title: www.cambridge.org/9781107050877

© Cambridge University Press 2014

This publication is in copyright. Subject to statutory exception and to the provisions of relevant collective licensing agreements, no reproduction of any part may take place without the written permission of Cambridge University Press.

First published 2014

Printed in the United States of America by Sheridan Books, Inc.

A catalogue record for this publication is available from the British Library

ISBN 978-1-107-05087-7 Hardback

Internal design based on tufte-latex.googlecode.com

Licensed under the Apache License, Version 2.0 (the "License"); you may not use this file except in compliance with the License. You may obtain a copy of the License at http://www.apache.org/licenses/LICENSE-2.0.

Unless required by applicable law or agreed to in writing, software distributed under the License is distributed on an "as is" basis, without warranties or conditions of any kind, either express or implied. See the License for the specific language governing permissions and limitations under the License.

 $Additional\ resources\ for\ this\ publication\ at\ www.cambridge.org/optimization models$

Cambridge University Press has no responsibility for the persistence or accuracy of URLs for external or third-party internet websites referred to in this publication, and does not guarantee that any content on such websites is, or will remain, accurate or appropriate.



Dedicated to my parents, and to Charlotte.

G. C.

Dedicated to Louis, Alexandre and Camille.

L. El G.





Contents

	Preface	page xi
1	Introduction	1
	1.1 Motivating examples	1
	1.2 Optimization problems	5
	1.3 Important classes of optimization problems	10
	1.4 History	14
	I Linear algebra models	19
2	Vectors and functions	21
	2.1 Vector basics	21
	2.2 Norms and inner products	28
	2.3 Projections onto subspaces	37
	2.4 Functions	43
	2.5 Exercises	53
3	Matrices	55
_	3.1 Matrix basics	55
	3.2 Matrices as linear maps	61
	3.3 Determinants, eigenvalues, and eigenvectors	64
	3.4 Matrices with special structure and properties	75
	3.5 Matrix factorizations	82
	3.6 Matrix norms	84
	3.7 Matrix functions	87
	3.8 Exercises	91
4	Symmetric matrices	97
'	4.1 Basics	97
	4.2 The spectral theorem	103
	4.3 Spectral decomposition and optimization	107
	4.4 Positive semidefinite matrices	110
	4.5 Exercises	118



viii contents

5	Singular value decomposition 5.1 Singular value decomposition 5.2 Matrix properties via SVD 5.3 SVD and optimization 5.4 Exercises	123 123 127 133 145
6	Linear equations and least squares 6.1 Motivation and examples 6.2 The set of solutions of linear equations 6.3 Least-squares and minimum-norm solutions 6.4 Solving systems of linear equations and LS problems 6.5 Sensitivity of solutions 6.6 Direct and inverse mapping of a unit ball 6.7 Variants of the least-squares problem 6.8 Exercises	151 151 158 160 169 173 177 183
7	Matrix algorithms 7.1 Computing eigenvalues and eigenvectors 7.2 Solving square systems of linear equations 7.3 QR factorization 7.4 Exercises	199 199 206 211 215
	II Convex optimization models	221
8	Convexity 8.1 Convex sets 8.2 Convex functions 8.3 Convex problems 8.4 Optimality conditions 8.5 Duality 8.6 Exercises	223 223 230 249 268 272 287
9	Linear, quadratic, and geometric models 9.1 Unconstrained minimization of quadratic functions 9.2 Geometry of linear and convex quadratic inequalities 9.3 Linear programs 9.4 Quadratic programs 9.5 Modeling with LP and QP 9.6 LS-related quadratic programs 9.7 Geometric programs 9.8 Exercises	293 294 296 302 311 320 331 335 341
10	Second-order cone and robust models 10.1 Second-order cone programs 10.2 SOCP-representable problems and examples	347 347 353



CONTENTS ix

	10.3 Robust optimization models 10.4 Exercises	368 377
11	Semidefinite models	381
	11.1 From linear to conic models	381
	11.2 Linear matrix inequalities	383
	11.3 Semidefinite programs	393
	11.4 Examples of SDP models	399
	11.5 Exercises	418
12	Introduction to algorithms	425
	12.1 Technical preliminaries	427
	12.2 Algorithms for smooth unconstrained minimization	432
	12.3 Algorithms for smooth convex constrained minimization	452
	12.4 Algorithms for non-smooth convex optimization 12.5 Coordinate descent methods	472
	12.6 Decentralized optimization methods	484 487
	12.7 Exercises	496
	III Applications	503
13	Learning from data	
1)	13.1 Overview of supervised learning	505 505
	13.2 Least-squares prediction via a polynomial model	507
	13.3 Binary classification	511
	13.4 A generic supervised learning problem	519
	13.5 Unsupervised learning	524
	13.6 Exercises	533
14	Computational finance	539
	14.1 Single-period portfolio optimization	539
	14.2 Robust portfolio optimization	546
	14.3 Multi-period portfolio allocation	549
	14.4 Sparse index tracking	556
	14.5 Exercises	558
15	Control problems	567
	15.1 Continuous and discrete time models	568
	15.2 Optimization-based control synthesis	571
	15.3 Optimization for analysis and controller design	579
	15.4 Exercises	586
16	Engineering design	591
	16.1 Digital filter design	591



X CONTENTS

16.2 Antenna array design	600
16.3 Digital circuit design	606
16.4 Aircraft design	609
16.5 Supply chain management	613
16.6 Exercises	622
Index	627
Timex	02/



Preface

OPTIMIZATION REFERS TO a branch of applied mathematics concerned with the minimization or maximization of a certain function, possibly under constraints. The birth of the field can perhaps be traced back to an astronomy problem solved by the young Gauss. It matured later with advances in physics, notably mechanics, where natural phenomena were described as the result of the minimization of certain "energy" functions. Optimization has evolved towards the study and application of algorithms to solve mathematical problems on computers.

Today, the field is at the intersection of many disciplines, ranging from statistics, to dynamical systems and control, complexity theory, and algorithms. It is applied to a widening array of contexts, including machine learning and information retrieval, engineering design, economics, finance, and management. With the advent of massive data sets, optimization is now viewed as a crucial component of the nascent field of data science.

In the last two decades, there has been a renewed interest in the field of optimization and its applications. One of the most exciting developments involves a special kind of optimization, convex optimization. Convex models provide a reliable, practical platform on which to build the development of reliable problem-solving software. With the help of user-friendly software packages, modelers can now quickly develop extremely efficient code to solve a very rich library of convex problems. We can now address convex problems with almost the same ease as we solve a linear system of equations of similar size. Enlarging the scope of tractable problems allows us in turn to develop more efficient methods for difficult, non-convex problems.

These developments parallel those that have paved the success of numerical linear algebra. After a series of ground-breaking works on computer algorithms in the late 80s, user-friendly platforms such as Matlab or R, and more recently Python, appeared, and allowed generations of users to quickly develop code to solve numerical prob-



xii PREFACE

lems. Today, only a few experts worry about the actual algorithms and techniques for solving numerically linear systems with a few thousands of variables and equations; the rest of us take the solution, and the algorithms underlying it, for granted.

Optimization, more precisely, convex optimization, is at a similar stage now. For these reasons, most of the students in engineering, economics, and science in general, will probably find it useful in their professional life to acquire the ability to recognize, simplify, model, and solve problems arising in their own endeavors, while only few of them will actually need to work on the details of numerical algorithms. With this view in mind, we titled our book Optimization Models, to highlight the fact that we focus on the "art" of understanding the nature of practical problems and of modeling them into solvable optimization paradigms (often, by discovering the "hidden convexity" structure in the problem), rather than on the technical details of an ever-growing multitude of specific numerical optimization algorithms. For completeness, we do provide two chapters, one covering basic linear algebra algorithms, and another one extensively dealing with selected optimization algorithms; these chapters, however, can be skipped without hampering the understanding of the other parts of this book.

Several textbooks have appeared in recent years, in response to the growing needs of the scientific community in the area of convex optimization. Most of these textbooks are graduate-level, and indeed contain a good wealth of sophisticated material. Our treatment includes the following distinguishing elements.

- The book can be used both in undergraduate courses on linear algebra and optimization, and in graduate-level introductory courses on convex modeling and optimization.
- The book focuses on *modeling* practical problems in a suitable optimization format, rather than on *algorithms* for solving mathematical optimization problems; algorithms are circumscribed to two chapters, one devoted to basic matrix computations, and the other to convex optimization.
- About a third of the book is devoted to a self-contained treatment of the essential topic of linear algebra and its applications.
- The book includes many real-world examples, and several chapters devoted to practical applications.
- We do not emphasize general non-convex models, but we do illustrate how convex models can be helpful in solving some specific non-convex ones.



PREFACE XIII

We have chosen to start the book with a first part on linear algebra, with two motivations in mind. One is that linear algebra is perhaps the most important building block of convex optimization. A good command of linear algebra and matrix theory is essential for understanding convexity, manipulating convex models, and developing algorithms for convex optimization.

A second motivation is to respond to a perceived gap in the offering in linear algebra at the undergraduate level. Many, if not most, linear algebra textbooks focus on abstract concepts and algorithms, and devote relatively little space to real-life practical examples. These books often leave the students with a good understanding of concepts and problems of linear algebra, but with an incomplete and limited view about *where* and *why* these problems arise. In our experience, few undergraduate students, for instance, are aware that linear algebra forms the backbone of the most widely used machine learning algorithms to date, such as the PageRank algorithm, used by Google's web-search engine.

Another common difficulty is that, in line with the history of the field, most textbooks devote a lot of space to eigenvalues of general matrices and Jordan forms, which do have many relevant applications, for example in the solutions of ordinary differential systems. However, the central concept of singular value is often relegated to the final chapters, if presented at all. As a result, the classical treatment of linear algebra leaves out concepts that are crucial for understanding linear algebra as a building block of practical optimization, which is the focus of this textbook.

Our treatment of linear algebra is, however, necessarily partial, and biased towards models that are instrumental for optimization. Hence, the linear algebra part of this book is not a substitute for a reference textbook on theoretical or numerical linear algebra.

In our joint treatment of linear algebra and optimization, we emphasize tractable models over algorithms, contextual important applications over toy examples. We hope to convey the idea that, in terms of reliability, a certain class of optimization problems should be considered on the same level as linear algebra problems: reliable models that can be confidently used without too much worry about the inner workings.

In writing this book, we strove to strike a balance between mathematical rigor and accessibility of the material. We favored "operative" definitions over abstract or too general mathematical ones, and practical relevance of the results over exhaustiveness. Most proofs of technical statements are detailed in the text, although some results



XIV PREFACE

are provided without proof, when the proof itself was deemed not to be particularly instructive, or too involved and distracting from the context.

Prerequisites for this book are kept at a minimum: the material can be essentially accessed with a basic understanding of geometry and calculus (functions, derivatives, sets, etc.), and an elementary knowledge of probability and statistics (about, e.g., probability distributions, expected values, etc.). Some exposure to engineering or economics may help one to better appreciate the applicative parts in the book.

Book outline

The book starts out with an overview and preliminary introduction to optimization models in Chapter 1, exposing some formalism, specific models, contextual examples, and a brief history of the optimization field. The book is then divided into three parts, as seen from Table 1.

Part I is on linear algebra, Part II on optimization models, and Part III discusses selected applications.

Table 1 Book outline.

	1	Introduction
I Linear	2	Vectors
algebra	3	Matrices
	4	Symmetric matrices
	5	Singular value
		decomposition
	6	Linear equations and
		least squares
	7	Matrix algorithms
II Convex	8	Convexity
optimization	9	Linear, quadratic,
		and geometric models
	10	Second-order cone
		and robust models
	11	Semidefinite models
	12	Introduction to
		algorithms
III Applications	13	Learning from data
	14	Computational finance
	15	Control problems
	16	Engineering design



PREFACE XV

The first part on linear algebra starts with an introduction, in Chapter 2, to basic concepts such as vectors, scalar products, projections, and so on. Chapter 3 discusses matrices and their basic properties, also introducing the important concept of factorization. A fuller story on factorization is given in the next two chapters. Symmetric matrices and their special properties are treated in Chapter 4, while Chapter 5 discusses the singular value decomposition of general matrices, and its applications. We then describe how these tools can be used for solving linear equations, and related least-squares problems, in Chapter 6. We close the linear algebra part in Chapter 7, with a short overview of some classical algorithms. Our presentation in Part I seeks to emphasize the optimization aspects that underpin many linear algebra concepts; for example, projections and the solution of systems of linear equations are interpreted as a basic optimization problem and, similarly, eigenvalues of symmetric matrices result from a "variational" (that is, optimization-based) characterization.

The second part contains a core section of the book, dealing with optimization models. Chapter 8 introduces the basic concepts of convex functions, convex sets, and convex problems, and also focuses on some theoretical aspects, such as duality theory. We then proceed with three chapters devoted to specific convex models, from linear, quadratic, and geometric programming (Chapter 9), to second-order cone (Chapter 10) and semidefinte programming (Chapter 11). Part II closes in Chapter 12, with a detailed description of a selection of important algorithms, including first-order and coordinate descent methods, which are relevant in large-scale optimization contexts.

A third part describes a few relevant applications of optimization. We included machine learning, quantitative finance, control design, as well as a variety of examples arising in general engineering design.

How this book can be used for teaching

This book can be used as a resource in different kinds of courses.

For a senior-level undergraduate course on *linear algebra and applications*, the instructor can focus exclusively on the first part of this textbook. Some parts of Chapter 13 include relevant applications of linear algebra to machine learning, especially the section on principal component analysis.

For a senior-level undergraduate or beginner graduate-level course on *introduction to optimization*, the second part would become the central component. We recommend to begin with a refresher on basic

XVI PREFACE

linear algebra; in our experience, linear algebra is more difficult to teach than convex optimization, and is seldom fully mastered by students. For such a course, we would exclude the chapters on algorithms, both Chapter 7, which is on linear algebra algorithms, and Chapter 12, on optimization ones. We would also limit the scope of Chapter 8, in particular, exclude the material on duality in Section 8.5. For a graduate-level course on *convex optimization*, the main material would be the second part again. The instructor may choose to emphasize the material on duality, and Chapter 12, on algorithms. The applications part can serve as a template for project reports.

Bibliographical references and sources

By choice, we have been possibly incomplete in our bibliographical references, opting to not overwhelm the reader, especially in the light of the large span of material covered in this book. With today's online resources, interested readers can easily find relevant material. Our only claim is that we strove to provide the appropriate search terms. We hope that the community of researchers who have contributed to this fascinating field will find solace in the fact that the success of an idea can perhaps be measured by a lack of proper references.

In writing this book, however, we have been inspired by, and we are indebted to, the work of many authors and instructors. We have drawn in particular from the largely influential textbooks listed on the side. We also give credit to the excellent course material of the courses EE364a, EE364b (S. Boyd), EE365 (S. Lall) at Stanford University, and of EE236a, EE236b, EE236c (L. Vandenberghe) at UCLA, as well as the slides that S. Sra developed for the course EE 227A in 2012 at UC Berkeley.

Acknowledgments

In the last 20 years, we witnessed many exciting developments in both theory and applications of optimization. The prime stimulus for writing this book came to us from the thriving scientific community involved in optimization research, whose members gave us, directly or indirectly, motivation and inspiration. While it would be impossible to mention all of them, we wish to give special thanks to our colleagues Dimitris Bertsimas, Stephen Boyd, Emmanuel Candès, Constantin Caramanis, Vu Duong, Michael Jordan, Jitendra Malik, Arkadi Nemirovksi, Yuri Nesterov, Jorge Nocedal, Kannan Ramchandran, Anant Sahai, Suvrit Sra, Marc Teboulle, Lieven Vandenberghe,

¹ S. Boyd and L. Vandenberghe, *Convex Optimization*, Cambridge University Press, 2004.

D. P. Bertsekas, Nonlinear Optimization, Athena Scientific, 1999.

D. P. Bertsekas (with A. Nedic, A. Ozdaglar), *Convex Analysis and Optimization*, Athena Scientific, 2003.

Yu. Nesterov, Introductory Lectures on Convex Optimization: A Basic Course, Springer, 2004.

A. Ben-Tal and A. Nemirovski, *Lectures on Modern Convex Optimization*, SIAM, 2001.

J. Borwein and A. Lewis, *Convex Analysis and Nonlinear Optimization: Theory and Examples*, Springer, 2006.



PREFACE XVII

and Jean Walrand, for their support, and constructive discussions over the years. We are also thankful to the anonymous reviewers of our initial draft, who encouraged us to proceed. Special thanks go to Daniel Lyons, who reviewed our final draft and helped improve our presentation.

Our gratitude also goes to Phil Meyler and his team at Cambridge University Press, and especially to Elizabeth Horne for her technical support.

This book has been typeset in Latex, using a variant of Edward Tufte's book style.