

#### **Electronic Sensor Design Principles**

Get up to speed with the fundamentals of electronic sensor design with this comprehensive guide and discover powerful techniques to reduce the overall design timeline for your specific applications.

It includes:

- A step-by-step introduction to a generalized information-centric approach for designing electronic sensors, demonstrating universally applicable practical approaches to speed up the design process.
- Detailed coverage of all the tools necessary for effective characterization and organization of the design process, improving overall process efficiency.
- A coherent and rigorous theoretical framework for understanding the fundamentals
  of sensor design, to encourage an intuitive understanding of sensor design
  requirements.

Emphasizing an integrated interdisciplinary approach throughout, this is an essential tool for professional engineers and graduate students keen to improve their understanding of cutting-edge electronic sensor design.

**Marco Tartagni** is Professor of Electrical Engineering at the Alma Mater Studiorum, University of Bologna. He has more than twenty-five years of experience in microelectronic design, with an emphasis on applied optical, biochemical, aerospace, and nanotechnology sensor design.



# **Electronic Sensor Design Principles**

MARCO TARTAGNI

Alma Mater Studiorum, University of Bologna





## **CAMBRIDGE**UNIVERSITY PRESS

University Printing House, Cambridge CB2 8BS, United Kingdom

One Liberty Plaza, 20th Floor, New York, NY 10006, USA

477 Williamstown Road, Port Melbourne, VIC 3207, Australia

314–321, 3rd Floor, Plot 3, Splendor Forum, Jasola District Centre, New Delhi – 110025, India

103 Penang Road, #05-06/07, Visioncrest Commercial, Singapore 238467

Cambridge University Press is part of the University of Cambridge.

It furthers the University's mission by disseminating knowledge in the pursuit of education, learning, and research at the highest international levels of excellence.

www.cambridge.org

Information on this title: www.cambridge.org/9781107040663

DOI: 10.1017/9781139629225

© Cambridge University Press 2021

This publication is in copyright. Subject to statutory exception and to the provisions of relevant collective licensing agreements, no reproduction of any part may take place without the written permission of Cambridge University Press.

First published 2021

Printed in the United Kingdom by TJ Books Limited, Padstow Cornwall

A catalogue record for this publication is available from the British Library.

Library of Congress Cataloging-in-Publication Data

Names: Tartagni, Marco, 1962- author.

Title: Electronic sensor design principles / Marco Tartagni, University of Bologna. Description: Cambridge, United Kingdom; New York, NY, USA: Cambridge

University Press, 2021. | Includes index.

Identifiers: LCCN 2020035625 | ISBN 9781107040663 (hardback) |

ISBN 9781139629225 (ebook)

Subjects: LCSH: Detectors – Design and construction.

Classification: LCC TK7872.D48 T37 2021 | DDC 681/.2-dc23

LC record available at https://lccn.loc.gov/2020035625

ISBN 978-1-107-04066-3 Hardback

Cambridge University Press has no responsibility for the persistence or accuracy of URLs for external or third-party internet websites referred to in this publication and does not guarantee that any content on such websites is, or will remain, accurate or appropriate.



To Marianna my grandmother and my daughter Ottavia, for teaching me how to feel, what artificial sensors do not, love



### **Contents**

Preface				page xv
Part I	Fundar	nentals		
1	Introduction			3
	1.1	Sensing	g as a Cognitive Process	4
	1.2	_	at a General Definition of Electronic Sensors	6
		1.2.1	Signals and Information	7
		1.2.2	The Simplest Case of an Analog-to-Digital Interface	9
		1.2.3	The Role of Errors	10
	1.3	Essentia	al Building Blocks of Electronic Sensors	15
	1.4		Origin of Uncertainty: Thermal Agitation	18
	1.5	Basic C	Constraints of Electronic Sensor Design	19
		Further	Reading	20
2	Sensor Modeling and Characterization			
	2.1	Signals		21
	2.2	The Ser	nsor Interface: The Deterministic Model	23
	2.3	Quasist	atic Ideal Characteristic and Sensitivity	25
	2.4	Signal Characterization		29
		2.4.1	Limits of the Quasistatic Characteristic and Frequency Dor	nain
			Representation	32
		2.4.2	Energetic Properties of Signals	35
	2.5	Time ar	nd Amplitude Quantization	41
	2.6	Sensor Acquisition Chains and Sensor Taxonomy		
	2.7	Deviations from Ideality: The Real Characteristic and Saturation		
	2.8	Deviations from Ideality: Errors		
		2.8.1	The Input-Output Duality of a Single Error	52
		2.8.2	Merge of Deterministic and Stochastic Models	53
		2.8.3	Estimation and Effects of Averaging	56
		2.8.4	Systematic Errors Due to Nonlinearity (Distortion)	59
		2.8.5	Characterization of Random and Systematic Errors	
			by Distributions	61
		2.8.6	Energy Properties of Random Signals	68



#### viii Contents

2.9	Input-Output Relationships for Random Error Distributions			
	2.9.1	Concept of Input-Referred Resolution Due to Random		
		Errors	76	
	2.9.2	Concept of Uncertainty and Its Relationship with		
		Resolution	79	
	2.9.3	Discretization of the Measurement Using Resolution Levels		
		in the Analog Domain	82	
2.10	System	atic Errors Due to Nonlinearity: The DC Approach	84	
2.11	Genera	lized Uncertainty and the Law of Propagation of Errors	89	
2.12				
	2.12.1	The Signal-to-Noise Ratio	91	
	2.12.2	The Concept of Dynamic Range	94	
	2.12.3	Is Dynamic Range the Maximum Signal-to-Noise Ratio?	98	
	2.12.4	Relationship Between Signal-to-Noise Ratio and		
		Dynamic Range for Defined Operating Ranges	101	
2.13	System	atic Errors Due to Nonlinearity: The AC Approach	102	
2.14	The Qu	nantization Process	106	
	2.14.1	Composition of Random and Quantization Noise and		
		Dithering	111	
	2.14.2	DC Resolution in A/D Converters	117	
	2.14.3	AC Characterization of A/D Converters by Effective		
		Number of Bits	118	
	2.14.4	Relationship Between Resolution and Effective Number		
		of Bits	122	
2.15	Precisio	on, Accuracy, and Trueness	124	
	2.15.1	Relationship Between Precision, Accuracy, and Dynamic		
		Range for Defined Operating Range	129	
	2.15.2	Inaccuracy Plots	130	
	2.15.3	Analysis of Interface and A/D Converter Chains	131	
	2.15.4	Design of the Interface with an A/D System	132	
2.16	Append	dix: Mean and Variance in Different Contexts	133	
	Further	Reading	134	
	-	n Optimization and Tradeoffs	135	
		ion of Random Errors by Averaging	135	
3.2		ion of Systematic Errors	138	
	3.2.1	Feedback Sensing	138	
	3.2.2	Dummy Differential Sensing	142	
	3.2.3	Electronic Calibration	143	
3.3		ble of Information in Sensor Acquisition Chains	144	
3.4		tion in Acquisition Chains	156	
	3.4.1	Gain and Resolution	156	
	3.4.2	The Resolution Rule in Acquisition Chains	160	

3



		Contents	IX
		3.4.3 Approach and Example of Application of the Resolution	
		Rule in Acquisition Chains	163
		3.4.4 Optimization of the Acquisition Chain from the	
		Resolution Point of View	165
		3.4.5 Optimal Choice of the A/D Converter	169
	3.5	Sampling, Undersampling, Oversampling, and Aliasing Filters	172
		3.5.1 Oversampling and Quantization	172
		3.5.2 Oversampling and Undersampling of White Noise	173
		3.5.3 Oversampling and Downsampling of Signals and Noise	174
	3.6	Power, Resolution, and Bandwidth Tradeoffs in Sensing	174
		3.6.1 The Role of Time	175
		3.6.2 The Role of Power	176
		3.6.3 The Role of the Dynamic Range	177
		3.6.4 Putting It All Together	178
		3.6.5 Beyond Thermal Noise Limited Figures of Merit	182
		3.6.6 The Role of Bandwidth in Acquisition Chains and Overall	
		Optimization	182
		3.6.7 Example: Noise Optimization in a Two-Stage Sensor	
		Interface	183
		3.6.8 On the Role of the Sensitivity	185
	3.7	General Rules for Sensing Design	186
		Further Reading	188
4	Overv	riew of Mathematical Tools	189
	4.1	Deterministic and Random Signals	189
		4.1.1 Characterization of Electrical Deterministic Signals	189
		4.1.2 Characterization of Random Signals	199
	4.2	Random Processes	205
	4.3	Concept of Ergodicity	209
		Convergence of Concepts Between Deterministic and Random	
		Variables	214
	4.5	Low-Pass Filtering of White Noise	216
	4.6	The Equivalent Noise Bandwidth	217
	4.7	Sum/Subtraction of Random Signals	219
	4.8	Physical Interpretation of Cross-Spectral Density	222
	4.9	The Lorentzian Form	224
		4.9.1 The Squared sinc Function and Its Relationship with the	
		Lorentzian	225
	4.10	The Campbell and Carson Theorems	227
	4.11	Power Spectral Density and Noise Density Notations	229
	4.12	The Sampling Process	230
	4.13	Appendix A: The Random Walk Process	232
	4.14	Appendix B: Summary of Important Relationships	234
		Further Reading	235
		-	



#### x Contents

5	Comp	ressive S	Sensing	236
	Marco	Chiani		
	5.1	Introdu	action	236
		5.1.1	Sampling Bandlimited Signals	236
		5.1.2	Sparse Signals	238
	5.2	Compr	essive Sensing	240
		5.2.1	Signals that are Sparse in a Transformed Domain	242
		5.2.2	Compressive Sensing in the Presence of Noise for	
			Compressible Signals	244
		5.2.3	Sparse Recovery Algorithms	244
	5.3	Summa	ary of Compressive Sensing	245
	5.4	Applica	ations	245
		5.4.1	Analog to Information Conversion	245
		5.4.2	Compressive Sensing for Image Acquisition: Single-Pixel	
			Camera	246
		5.4.3	Compressive Sensing for Magnetic Resonance Imaging and for	
			Biomedical Signal Processing Applications	246
		Referen	nces	247
Part II	Noise a	ınd Elec	tronic Interfaces	
6	The O	rigin of I	Noise	251
	6.1	Therma	al Noise	251
		6.1.1	A Simplified Mechanical Model	251
		6.1.2	Electronic Thermal Noise from the Experimental	
			Viewpoint	256
		6.1.3	Thermal Noise Power Spectra Density Calculation:	
			The Nyquist Approach	257
		6.1.4	Thermal Noise PSD Calculation Using an	
			Energy Tank	260
		6.1.5	The kTC Noise	262
		6.1.6	Thermal Noise in Resistor-Capacitor Transients	264
	6.2	Current	t Noise (Shot Noise)	266
		6.2.1	Shot Noise from the Experimental Viewpoint	266
		6.2.2	Characteristics of Current (Shot) Noise as a Poisson	
			Process	267
		6.2.3	Calculation of Current (Shot) Noise Power Spectral	
			Density	270
		6.2.4	Relationship Between Shot Noise and Thermal Noise	271
	6.3	Noise i	n Optical Detectors	272
		6.3.1	Noise Photocurrents	272
		6.3.2	Shot Noise in Photosites	273



		Contents	Xİ
	6.4	Flicker or 1/f Noise	274
		6.4.1 The Issue of Stationary in Flicker Noise and Its Memory	280
	6.5	The Colors of Noise	282
		6.5.1 Autocorrelation Functions of Noises	283
	6.6	Thermomechanical Noise	284
		6.6.1 Quick Review of Second-Order Systems	284
		6.6.2 Bandwidth and Noise Bandwidth of the Bandpass	
		Function	287
		6.6.3 Physical Models	289
		6.6.4 Thermomechanical Noise	292
	6.7	Phase Noise	294
		6.7.1 The Total Oscillator Noise	304
		6.7.2 Characterization of Phase Noise from Total Noise	
		from a Modulation Viewpoint	306
		6.7.3 Jitter and Its Estimation from Phase Noise	308
		Further Reading	312
7	Noise	in Electronic Devices and Circuits	313
	7.1	Thermal Noise Limited Signal-to-Noise Ratio and Bandwidth	313
	7.2	Pink and White Noise Combination	314
	7.3	Calculation of Total Noise in Linear Circuits	318
	7.4	Input-Referred Noise in Circuits	320
		Noise Factor and Optimal Noise Performance	325
	7.6	Example: Noise in Junction Transistors	331
	7.7	Example: Noise in Metal–Oxide–Semiconductor Transistors	335
	7.8	Input-Referred Noise Representation in the Spectrum Domain	338
	7.9	Noise in Operational Amplifier Configurations	342
		7.9.1 Signal and Noise Gain Paths	346
		7.9.2 Example: Noise Calculation for an Operational Amplifier	348
		7.9.3 Noise Efficiency Factor and Power Efficiency Factor	349
	7.10	Capacitively Coupling Amplifier Techniques	350
		7.10.1 Continuous-Time Techniques for Voltage Sensing	350
		7.10.2 Continuous-Time Techniques for Current Sensing	353
		7.10.3 Capacitively Coupling Amplifiers in Discrete-Time	256
		Techniques	356
		7.10.4 Reset Techniques and Related Problems	357
		7.10.5 Summary of Interface Techniques Using a Capacitively	262
	7 11	Coupling Trans-Impedance Amplifier	362
	7.11	Noise Folding in Discrete-Time Techniques	363
		<ul><li>7.11.1 Noise in Discrete-Time Capacitively Coupling Amplifiers</li><li>7.11.2 Summary of Input-Referred Noises in Common Discrete-Time</li></ul>	367
		Interfaces	368
		7.11.3 Resolution Optimization of a Cascade of Amplifiers	370
		Further Reading	372
		$\boldsymbol{\varepsilon}$	



#### xii Contents

•	Datas	Aion Tookningo	274
8	8.1	ction Techniques	374
	8.1	From Single-Ended to Differential Architectures	374
		8.1.1 Noise or Interference? The Advantage of the Fully Differential Approach	374
		**	375
	0.2	8.1.2 Example: Fully Differential Charge Amplifiers	
	8.2	$\varepsilon$	376
	0.2	Rationical Reducat	381
	8.3	Capacitive Sensing	382
		8.3.1 Example: Capacitive Accelerometer	386
	0.4	8.3.2 AC Capacitive Sensing	386
		1	387
	8.5	Integration of a Sensing System Using a Sigma–Delta Modulator	200
		Feedback	389
		8.5.1 The Sigma–Delta Converter Concept	389
		8.5.2 Example: The Electrostatic Feedback Accelerator	394
	8.6	The Correlated Double Sampling Technique	395
	8.7	The Lock-In Technique	398
	8.8	Oscillator-Based Sensing	402
		8.8.1 Time-to-Digital Conversion Sensing	407
		8.8.2 Frequency-to-Digital Conversion Sensing	414
	8.9	Time-Based Techniques for Resistance and Capacitive Sensing	416
		8.9.1 Relaxation Oscillator Technique	416
		8.9.2 Bang–Bang Phase Locked Loop Sensing Technique	417
		8.9.3 Frequency Locked Loop Sensing Technique	419
		Further Reading	420
Part III	Selecte	ed Topics on Physics of Transduction	
9	Selec	ted Topics on Photon Transduction	425
	9.1	Overview of Basic Concepts	425
		9.1.1 Electromagnetic and Visible Spectra	425
		9.1.2 Photometry/Radiometry Quantities	428
		9.1.3 Power Transfer in Image Projection Systems	438
	9.2	Blackbody Emission	441
	9.3	Photon Interaction with Semiconductors	445
	9.4	Image Sensor Devices and Systems	451
		9.4.1 Photosite Examples: CCDs and Photodiodes	451
		9.4.2 Continuous-Time Readout Mode	455
		9.4.3 The Storage Mode Concept	457
	9.5	Noise in Photodiodes	460
	9.6	CMOS Area Image Sensor Architectures	463
	9.7	Appendix: Summary of Photometry/Radiometry Definitions	466
		Further Reading	467



			Contents	s xiii	
10	Selected Topics on Ionic-Electronic Transduction				
	10.1		ical Thermodynamics: Background Overview	468	
		10.1.1	Maxwell-Boltzmann Statistics	468	
		10.1.2	Some Applications of the Maxwell-Boltzmann Statistics	472	
			Relationship Between Potentials in a Redox	475	
			Drift and Diffusion Effects	478	
	10.2	Electri	cal Conduction and Polarization of Matter	483	
		10.2.1	Conductivity	483	
		10.2.2	Polarization of Matter	485	
		10.2.3	Complex Dielectric Constant and Debye Relaxation		
			Model	489	
		10.2.4	The Double Layer Interface in Ionic Solutions	497	
		10.2.5	Faradaic Processes in Electrolytic Cells	504	
		10.2.6	Charge and Mass Transfer Effects	506	
		10.2.7	Complex Effects of Diffusion	510	
		10.2.8	Diffusion in Finite-Length Conditions	513	
		10.2.9	Putting It All Together: The Randles Model	515	
		10.2.10	0 Model Analysis by Cole–Cole and Bode Plots	515	
	10.3	Bioche	emical Sensing	521	
		10.3.1	Basic Principles	521	
		10.3.2	Electrode Polarization Approaches	524	
		10.3.3	Applications of the Potentiostat	528	
	10.4	Biosen	sing for Electrophysiology	531	
		10.4.1	Biopotential Sensors	531	
		10.4.2	Biosensing for Intracellular Recordings	540	
		Furthe	r Reading	543	
11	Selec	ted Toni	cs on Mechanical and Thermal Transduction	544	
••	11.1 Overview of Basic Concepts				
			Strain and Stress in One Dimension	544 544	
		11.1.2	Strain and Stress Applied to Orthogonal Axes	546	
		11.1.3	The Stress Tensor	548	
		11.1.4		554	
		11.1.5	Relationships Between Shear and Stress in Three	334	
		11.1.5	Dimensions	555	
		11.1.6	Elasticity for Isotropic Materials	557	
		11.1.7	Deformation in Simple Structures	558	
	11.2		esistivity	558	
	11.2	11.2.1	Piezoresistivity in Metals and Alloys	562	
		11.2.2	Piezoresistivity in Crystals	563	
				202	



xiv	Contents			
	11.3	Piezoelectricity		564
		11.3.1 Direct and Converse	Piezoelectric Effect	568
		11.3.2 Piezoelectricity in Th	ree Dimensions	576
	11.4	Resistance Temperature Sensi	ng	579
		11.4.1 Resistance Temperat	ure Detectors	580
		11.4.2 Thermistors		582
	11.5	Application of Force and Tem	perature Resistance Sensors	584
		11.5.1 Implementation and	Readout Techniques of Resistive	
		Sensors		584
		11.5.2 Errors and Influence	Variables in Strain Gauges	587
		•	For Force Sensors and Error Compensation	
		Techniques		588
			electromechanical Systems	591
		11.5.5 Errors in Resistance	-	592
	11.6	Appendix: Notations Used in	the Chapter	593
		Further Reading		593
Part IV	Proble	s and Solutions		
12	Problems and Solutions			597
	Marco 12.1	rescentini		597
	12.1	Problems Solutions		603
	12.2	Solutions		003

Index

622



#### **Preface**

One question I have constantly pondered in the course of my professional life is whether there are general principles in the sensing process that can be applied to the designing of electronic sensors. The aim of this book is to guide the reader along a train of argument leading to an affirmative answer to that question, which provided the title.

Textbooks outlining techniques of sensor design often follow one of two quite contrasting approaches. The first is to focus on one highly specific context linked to a single application. The second hangs the treatment on a broad classification of transduction and architecture techniques. The latter approach leads to the false idea that sensor design boils down to a series of separate cases classified according to their specific application. Such a view may be erroneously encapsulated in the idea that the highly interdisciplinary nature of this field consists in a reasoned assembly of various points geared only to enhance the design efficiency. In actual fact, interdisciplinarity in this domain (which calls for highly different techniques and models ranging from the mathematics of random processes to the science of measurements, signal conversion and processing, information theory, and transduction physics) reveals that the various different subjects are nothing but contextualizations of a few general principles. This book thus sets out to define a general methodology behind the designing of electronic sensors, regardless of the individual application: this will markedly reduce design time and enable the essential design variables to be swiftly identified.

One basic line of inquiry that the book pursues is the role of *information* in the sensing process. This led to a broader definition of *sensor*, focusing on its ability to extract information from the environment. Whereas information theory stemmed from the area of electric communications in which codes may be optimized so as to maximize the amount of data transmitted on the channel, with sensing, the perspective has to be reversed. Here, since the source of information pertains to observed nature, it cannot, as a rule, be altered, and design optimization can be seen as the maximizing of information conveyed by the process. It is in this context that certain basic definitions of sensor physics have been revised. By way of example, we will describe the concept of resolution not just in its original accepted meaning, but highlighting its connections to the amount of information conveyed in the sensing process: an aspect that will enable us to find effective methods of optimizing electronic sensor design.

Writing a textbook is a complex process in which the author is often torn between opposing courses of action. On the one hand, he or she will tend to go for formal rigor of presentation vis-à-vis the scientific community above all. On the other, the desire is



#### xvi Preface

to outline the subject as clearly as possible for the beginner, if possible, favoring an intuitive approach based on solving certain conceptual problems, sometimes at the expense of formal rigor. Depending on the target audience, the author will juggle between these two opposing approaches.

Yet if I consider my own teaching experience more closely, it has shown some surprising features. In many (though not all) cases, students to begin with prefer a formal approach to the discipline since that confers an apparent security; they are suspicious about the kind of treatment that starts from concrete examples and ends up in abstract concepts. On the other hand, those already familiar with the discipline will tend to focus more on the principles of the subject, picking out points that had previously eluded them. This accounts for the reaction to certain seminal scientific textbooks that favor a bottom-up approach to the subject. For all their conceptual rigor, they are unlikely to be popular as student course books, since by definition the abstracting process calls for a long period of maturation in the mind of a student. With this book, I have hence adopted a style that mixes the two: the intuitive approach is designed not around abstract hypotheses, but concrete numerical examples, concluding with a due degree of formalism suitable for the task of summing up.

The text is based on two courses I have taught for several years at the Cesena Campus of Bologna University. I must thank my past and present undergraduate, graduate, and Ph.D. students, first and foremost, for their responsiveness and dialogue that enabled me to correct and hone this experience of tuition. I find it hard to imagine writing a textbook without the critical backing of a course dealing with the subject. In drafting the book, I adopted a number of different approaches: trying them out on the course helped me choose among them. My thanks go to many people with whom it has been a pleasure to exchange notes. First of all, Alessandro Piovaccari for his friendship, constant support and encouragement, and above all for firing my imagination about basic principles of the subject. I must also thank Victor Zhirnov for points to do with the limits of sensing, Marco Chiani for information theory, Davide Dardari for the theory of estimation, Aldo Romani for piezoelectric transduction, Alberto Corigliano for mechanical transduction, Hywel Morgan for ionic transduction and biosensor physics, and Marco Crescentini for our many discussions on electronic noise and measurement science. Also, a special thanks to my colleagues Alessandra Costanzo, Alessandro Talamelli, Emanuele Giordano, Luigi Ragni, Elena Babini, Annachiara Berardinelli, Mauro Ursino, and Enrico Sangiorgi for scientific collaboration, friendship, and constant and effective support in this work. My thanks, too, to Roberto Trolli for various points to do with the philosophy of science, raised by him over many years of fraternal friendship and endless and engaging discussions. A special thanks to my older brother Flavio Tartagni for intriguing me into experimental science when I was a child. Last, and definitely not least, my sincere thanks to my publishers, Cambridge University Press, and in particular to Julie Lancashire, for the unreserved confidence they passed on to me from the outset. My thanks to all the editorial staff for their patience, constant assistance, and suggestions over these past years.

One important restriction must be noted in the range of subjects covered by the book. It analyzes sensors whose resolution is constrained by thermal noise – the area



Preface

χvii

often referred to as "thermal noise limited sensors" - and by sensors limited by shot noise. Such an approach is suited to most sensors used at room temperature and for general applications. Analysis of the origin of the noise is thus briefly introduced from the angle of classical statistical mechanics. Of course, it is evident that in sensing and measurement science, the extreme outer limits are dictated by the uncertainty principle, the restraints of which are felt in far less usual cases than those here described. For this reason, sensors based on quantum mechanics principles will not figure in here.

The book falls into three parts. The first one contextualizes general concepts by definitions of design variables, characterization parameters, signals, and errors. This framework will discuss the design tradeoffs under the information theory viewpoint.

The second part focuses on the physical origin of the noise and its role in electronic interfaces design. Here, general design optimization approaches, techniques, and architectures are analyzed, also covering the time-domain sensing techniques.

Finally, the third part deals with selected topics on three different aspects of transduction physics: optical, ionic, and mechanical. The section makes no claim to cover all sides to transduction but only gives examples of typical applications. However, the latter part is not a bare addition to this book since physical transduction is an essential step of the overall sensor acquisition chain, and it should be considered a processing block like all the others in the design process. Therefore, I considered it necessary to show transduction examples to practice the overall sensor design optimization.

Chapter 1 introduces various concepts concerning information and signals, which will be dealt with in later chapters but meanwhile yield a definition of the artificial sensor. Chapter 2 introduces a number of basic parameters characterizing sensor physics, including precision/accuracy and respective tradeoffs, along with relevant figures of merits. Chapter 3 analyzes the main sensor design tradeoffs under the information theory perspective. Chapter 4 lists certain important features of the mathematical methods used in analyzing and synthesizing sensor systems. Chapter 5, by M. Chiani (Alma Mater, University of Bologna), introduces the compressive sensing approach.

Chapter 6 deals with the origins and models of noise in various contexts, including the time domain, such as phase noise. Chapter 7 provides models for calculating and optimizing noise in the case of devices and simple electronic circuits. Chapter 8 covers more complex electronic systems of extracting information that operates in signal and time-space.

Chapter 9 introduces a number of concepts of photonic transduction with particular reference to the photodiode and its configurations in area sensors. Chapter 10 deals with the ionic-electronic transduction that underlies biosensing. That chapter also provides an opportunity to cover some noise issues in biosensors, especially in biopotential sensing. Lastly, Chapter 11 tackles mechanical transduction with particular attention to piezoresistivity and piezoelectricity. The chapter also considers some examples in which resistive mechanical sensors are applied. Finally, Chapter 12 by M. Crescentini (Alma Mater, University of Bologna) offers a collection of electronic sensor design problems and related solutions.

The book is dedicated to the memory of Professors Silvio Cavalcanti and Claudio Canali.