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Excerpt

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1

Preliminaries

In this chapter we will discuss some preliminary material we will use throughout the book.

1.1 Differential calculus

Let us begin with an outline, without proofs, of differential calculus in Banach spaces. For proofs and more details we refer to [20], Chapters 1 and 2.

The Fréchet derivative. Let X, Y be Banach spaces and let $L(X, Y)$ denote the space of linear continuous maps from X to Y . For $A \in L(X, Y)$ we will often write Ax or $A[x]$ instead of $A(x)$. Endowed with the norm

$$\|A\|_{L(X,Y)} = \sup\{\|Ax\|_Y : \|x\|_X \leq 1\}, \quad A \in L(X, Y),$$

$L(X, Y)$ is a Banach space. If $U \subset X$ is an open set, $C(U, Y)$ denotes the space of continuous maps $f : U \rightarrow Y$.

Definition 1.1 We say that $f : U \rightarrow Y$ is (Fréchet) differentiable at $u \in U$ with derivative $df(u) \in L(X, Y)$ if

$$f(u + h) = f(u) + df(u)[h] + o(\|h\|), \quad \text{as } h \rightarrow 0.$$

f is said differentiable on U if it is differentiable at every point $u \in U$.

From the definition it follows that if f is differentiable at $u \in U$ then f is continuous at u .

In order to find the derivative of a map f one can evaluate, for all $h \in X$, the limit

$$\lim_{\varepsilon \rightarrow 0} \frac{f(u + \varepsilon h) - f(u)}{\varepsilon} \stackrel{\text{def}}{=} A_u h.$$

If $A_u \in L(X, Y)$ and if the map $u \mapsto A_u$ is continuous from U to $L(X, Y)$, then f is differentiable at u and $df(u) = A_u$. We will often use $f'(u)$ instead of $df(u)$.

Let $f : X \times Y \rightarrow Z$, and consider the map $f_u : u \mapsto f(u, v)$, respectively $f_v : v \mapsto f(u, v)$. The *partial derivative* of f with respect to u , respectively v , at $(u, v) \in X \times Y$ is defined by $\partial_u f(u, v) = df_u(u)$, respectively $\partial_v f(u, v) = df_v(v)$. In particular, $\partial_u f(u, v) \in L(X, Z)$ and $\partial_v f(u, v) \in L(Y, Z)$. It is easy to see that if $f : X \times Y \rightarrow Z$ is differentiable at (u, v) , then f is partially differentiable and $\partial_u f(u, v)[h] = df_v(u)[h] = df(u, v)[h, 0]$, respectively $\partial_v f(u, v)[k] = df_u(v)[k] = df(u, v)[0, k]$. Furthermore, the following result holds.

Proposition 1.2 *If f possesses the partial derivative with respect to u and v in a neighbourhood \mathcal{N} of (u, v) and the maps $u \mapsto \partial_u f$ and $v \mapsto \partial_v f$ are continuous in \mathcal{N} , then f is differentiable at (u, v) and*

$$df(u, v)[h, k] = \partial_u f(u, v)[h] + \partial_v f(u, v)[k].$$

In the sequel, if no confusion arises, we will write f'_u, f'_v instead of $\partial_u f, \partial_v f$, respectively.

Higher order derivatives. Let f be differentiable on U and the map $X \mapsto L(X, Y), u \mapsto df(u)$, be differentiable at $u \in U$. The derivative of such a map at u is a second derivative: $d^2f(u) \in L(X, L(X, Y))$. From the canonical isomorphism between $L(X, L(X, Y))$ and $L_2(X, Y)$, the space of bilinear maps from X to Y , we can and will consider $d^2f(u)$ belonging to $L_2(X, Y)$. By induction on k we can define the k th derivative $d^k f(u) \in L_k(X, Y)$, the space of k -linear maps from E into \mathbb{R} . If f is k times differentiable at every point of U , we say that f is k times differentiable on U .

We will use the following notation.

- C^k maps. If f is k times differentiable on U and the application $U \mapsto L_k(X, Y), u \mapsto d^k f(u)$, is continuous, we say that $f \in C^k(U, Y)$.
- $C^{0,\alpha}$ maps. If $f \in C(U, Y)$ satisfies

$$\sup \left[\frac{\|f(u) - f(v)\|_Y}{\|u - v\|_X^\alpha} : u, v \in U, u \neq v \right] < +\infty,$$

for some $\alpha \in (0, 1]$, we say that $f \in C^{0,\alpha}(U, Y)$. If $\alpha < 1$, respectively $\alpha = 1$, these maps are nothing but the *Hölder continuous* maps, respectively *Lipschitz* maps.

- $C^{k,\alpha}$ maps. If $f \in C^k(U, Y)$ and $d^k f(u) \in C^{0,\alpha}(U, L_k(X, Y))$, we say that $f \in C^{k,\alpha}(U, Y)$.

Let $f \in C^k(U, Y)$ and suppose that $u, h \in U$ be such that $u + th \in U$ for all $t \in [0, 1]$. Since one has

$$\frac{d^r}{dt^r} f(u + th) = d^r f(u + th)[h]^r, \quad [h]^r = \underbrace{[h, \dots, h]}_{r \text{ times}}, \quad r = 1, \dots, k,$$

the Taylor formula for $t \mapsto f(u + th)$ yields

$$f(u + h) = f(u) + df(u)[h] + \dots + \frac{1}{k!} d^k f(u)[h]^k + o(\|h\|^k).$$

Local inversion and implicit function theorems. Let $f \in C(U, Y)$, $u^* \in U$ and $v^* = f(u^*) \in Y$. We say that f is *locally invertible* at u^* if there exist neighbourhoods U^* of u^* and V^* of v^* and a map $g \in C(V^*, U^*)$ such that

$$g(f(u)) = u, \quad \forall u \in U^*, \quad f(g(v)) = v, \quad \forall v \in V^*.$$

The map g will be denoted by f^{-1} .

Theorem 1.3 (Local inversion theorem) *Suppose that $f \in C^1(U, Y)$ and that $df(u^*)$ is invertible (as a linear map in $L(X, Y)$). Then f is locally invertible at u^* , f^{-1} is of class C^1 and*

$$df^{-1}(v) = (df(u))^{-1}, \quad \forall v \in V^*, \quad \text{where } u = f^{-1}(v).$$

Furthermore, if $f \in C^k(U, Y)$ then f^{-1} is of class C^k , as well.

Let T, X be Banach spaces, $\Lambda \subset T$, $U \subset X$ be open subsets.

Theorem 1.4 (Implicit function theorem) *Let $f \in C^k(\Lambda \times U, Y)$, $k \geq 1$, and let $(\lambda^*, u^*) \in \Lambda \times U$ be such that $f(\lambda^*, u^*) = 0$. If $f'_u(\lambda^*, u^*) \in L(X, Y)$ is invertible, then there exist neighbourhoods Λ^* of λ^* , U^* of u^* and a map $g \in C^k(\Lambda^*, X)$ such that*

$$f(\lambda, u) = 0, \quad (\lambda, u) \in \Lambda^* \times U^* \Leftrightarrow u = g(\lambda).$$

Moreover one has that

$$g'(\lambda) = -(f'_u(p))^{-1} \circ f'_\lambda(p), \quad \text{where } p = (\lambda, g(\lambda)), \lambda \in \Lambda^*.$$

1.2 Function spaces

We will deal with *bounded domains* Ω contained in the Euclidean n -dimensional space \mathbb{R}^n . We will mainly work in the following spaces of functions $u : \Omega \rightarrow \mathbb{R}$:

- $L^p(\Omega)$, Lebesgue spaces with norm $\|\cdot\|_{L^p}$;
- $H^{k,p}(\Omega)$, Sobolev spaces with norm $\|\cdot\|_{H^{k,p}}$;
- $C_0^\infty(\Omega)$, the space of functions $u \in C^\infty(\Omega)$ with compact support in Ω ;
- $H_0^1(\Omega)$, the closure of $C_0^\infty(\Omega)$ in $H^{1,2}(\Omega)$.

For functions in $H_0^1(\Omega)$ the *Poincaré inequality* holds:

$$\int_{\Omega} |u|^2 dx \leq c \int_{\Omega} |\nabla u|^2 dx,$$

where $c = c(\Omega)$ is a constant (possibly depending on Ω but independent of u).

As a consequence of the Poincaré inequality it follows that

$$\|u\| = \left(\int_{\Omega} |\nabla u|^2 dx \right)^{1/2}$$

is a norm equivalent to the standard one $\|u\|_{H_0^1}$.

Theorem 1.5 (Sobolev embedding theorem) *Let Ω be a bounded domain in \mathbb{R}^n with Lipschitz boundary $\partial\Omega$ and let $k \geq 1, 1 \leq p \leq \infty$.*

- (i) *If $kp < n$, then $H^{k,p}(\Omega) \hookrightarrow L^q(\Omega)$ for all $1 \leq q \leq np/(n - kp)$; the embedding is compact provided $1 \leq q < np/(n - kp)$.*
- (ii) *If $kp = n$, then $H^{k,p}(\Omega) \hookrightarrow L^q(\Omega)$ for all $1 \leq q < \infty$, and the embedding is compact.*
- (iii) *If $kp > n$, then $H^{k,p}(\Omega) \hookrightarrow C^{0,\alpha}(\Omega)$, where*

$$\alpha = \begin{cases} k - n/p & \text{if } k - n/p < 1 \\ 1 & \text{if } k - n/p > 1. \end{cases}$$

If $k - n/p = 1$, the embedding holds for every $\alpha \in [0, 1)$.

When we deal with $H_0^1(\Omega)$ the requirement that $\partial\Omega$ is Lipschitz can be eliminated. For future references let us state explicitly what Theorem 1.5 becomes in such a case. We set

$$2^* = \begin{cases} 2n/(n - 2) & \text{if } n > 2 \\ +\infty & \text{if } n = 2. \end{cases}$$

Theorem 1.6 *Let Ω be a bounded domain in \mathbb{R}^n . Then*

- (i) *if $n > 2$, then $H_0^1(\Omega) \hookrightarrow L^q(\Omega)$ for all $1 \leq q \leq 2^*$; the embedding is compact provided $1 \leq q < 2^*$;*
- (ii) *if $n = 2$, then $H_0^1(\Omega) \hookrightarrow L^q(\Omega)$ for all $1 \leq q < \infty$;*
- (iii) *if $n < 2$, then $H_0^{1-p}(\Omega) \hookrightarrow C^{0,\alpha}(\Omega)$, where $\alpha = 1 - n/2$.*

1.3 Nemitski operators

Let $f : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$. If $u : \Omega \rightarrow \mathbb{R}$ is a measurable real valued function, we can consider the map $u \mapsto f(u)$, where $f(u)$ is the real valued function defined on Ω by setting

$$f(u)(x) = f(x, u(x)).$$

Such a map is called the *Nemitski operator* associated to f and will be denoted with the same symbol f . For a discussion of the continuity and differentiability properties of Nemitski operators we refer to [20], Chapter 1, Section 2. Here we want to recall the following result.

Theorem 1.7 *Let $\alpha, \beta \geq 1$. Suppose that $f : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ satisfies*

- (f.0)** *$f(x, t)$ is measurable with respect to $x \in \Omega$ for all $t \in \mathbb{R}$ and is continuous with respect to $t \in \mathbb{R}$ for a.e. $x \in \Omega$,*

and that there exists $a_1 \in L^\beta(\Omega)$ and $a_2 > 0$ such that

$$|f(x, u)| \leq a_1(x) + a_2|u|^{\alpha/\beta} \quad \forall (x, u) \in \Omega \times \mathbb{R}, \quad (\alpha, \beta \geq 1). \quad (1.1)$$

Then the Nemitski operator f is continuous from $L^\alpha(\Omega)$ to $L^\beta(\Omega)$.

Condition (f.0) is also called the *Caratheodory condition* and a function $f(x, t)$ satisfying (f.0) is usually called a *Caratheodory function*. In most of the concrete applications we will deal with the functional space $H_0^1 = H_0^1(\Omega)$. In such a case, we shall suppose that f satisfies

- (f.1)** *there exists $a_1 \in L^{2n/(n+2)}(\Omega)$ and $a_2 > 0$ such that*

$$|f(x, u)| \leq a_1(x) + a_2|u|^p \quad \forall (x, u) \in \Omega \times \mathbb{R}, \quad (1.2)$$

where $p < 2^* - 1$.

In some cases we will weaken (f.1) requiring

- (f.1')** *f satisfies (1.2) with $p \leq 2^* - 1$.*

The class of functions f which are locally Hölder continuous and satisfy (f.1) or (f.1'), will be denoted by \mathbb{F}_p .

Let us point out that, in many cases, we could deal with functions that satisfy (f.0), instead of being locally Hölder continuous; see, for example, Remark 1.9 below. The advantage of working with the class \mathbb{F}_p is that we get classical solutions of elliptic equations we deal with, not merely weak solutions.

Moreover, in the sequel we also take $n > 2$. If $n = 1, 2$ one uses the stronger forms of the Sobolev embedding theorem and the arguments below require minor changes.

If (f.1') holds then, according to Theorem 1.7, one has that

$$f \in C(L^{2^*}, L^{2n/(n+2)}). \tag{1.3}$$

Moreover, setting

$$F(x, u) = \int_0^u f(x, s) \, ds,$$

it follows that

$$|F(x, u)| \leq a_1|u| + a_2|u|^{p+1},$$

with $p + 1 \leq 2^*$. Since $H_0^1 \hookrightarrow L^{2^*}$ then $F(\cdot, u(\cdot)) \in L^1$ provided $u \in H_0^1$ and it makes sense to consider the map $\Phi : H_0^1 \rightarrow \mathbb{R}$ defined by

$$\Phi(u) = \int_{\Omega} F(x, u) \, dx. \tag{1.4}$$

One can show, see Theorem 2.9 of [20], that Φ is of class C^1 on H_0^1 and

$$d\Phi(u)[v] = \int_{\Omega} f(x, u)v \, dx.$$

Let us point out that, as remarked before, $f(x, u) \in L^{2n/(n+2)}$ while $v \in H_0^1 \subset L^{2^*}$; hence $f(x, u)v \in L^1$ so that the right hand side of the preceding formula makes sense.

Next, suppose that $f \in \mathbb{F}_p$ with $1 < p < (n + 2)/(n - 2)$, and let $u_n \rightarrow u$, weakly in H_0^1 . Since $p + 1 < 2^*$, the embedding of $H_0^1 \hookrightarrow L^{p+1}$ is compact and thus, up to a subsequence, $u_n \rightarrow u$ strongly in L^{p+1} . This immediately implies that

$$\Phi(u_n) \rightarrow \Phi(u),$$

and shows that Φ is weakly continuous. Similarly, from Theorem 1.7 we infer that $f(u_n) \rightarrow f(u)$ in $L^\alpha(\Omega)$, with $\alpha = (p + 1)/p$. Using the Hölder inequality

we get

$$\begin{aligned} |\mathrm{d}\Phi(u_n)[v] - \mathrm{d}\Phi(u)[v]| &\leq \left[\int_{\Omega} |f(x, u_n) - f(x, u)|^{\alpha} \mathrm{d}x \right]^{1/\alpha} \left[\int_{\Omega} |v|^{p+1} \mathrm{d}x \right]^{1/(p+1)} \\ &= \|f(u_n) - f(u)\|_{L^{\alpha}} \|v\|_{L^{p+1}}. \end{aligned}$$

Since $p + 1 < 2^*$ we deduce that $\|v\|_{L^{p+1}} \leq c \|v\|_{H_0^1}$, where $c > 0$ is a constant independent of v . In conclusion, we infer that

$$\|\mathrm{d}\Phi(u_n) - \mathrm{d}\Phi(u)\| \leq c \|f(u_n) - f(u)\|_{L^{\alpha}},$$

and this shows that $\mathrm{d}\Phi$ is a compact operator. Let us collect the above results in the following.

Theorem 1.8 *Suppose that $f \in \mathbb{F}_p$ with $1 < p \leq (n + 2)/(n - 2)$ and let Φ be defined on $H_0^1(\Omega)$ by (1.4). Then $\Phi \in C^1(H_0^1, \mathbb{R})$.*

Furthermore, if $f \in \mathbb{F}_p$ with $1 < p < (n + 2)/(n - 2)$, then Φ is weakly continuous and $\mathrm{d}\Phi$ is a compact operator.

Remark 1.9 The first (respectively second) statement holds true if we suppose that f satisfies $(f.0)$ and $(f.1')$, respectively $(f.0)$ and $(f.1)$. Furthermore, if f is Lipschitz, respectively of class C^k , with respect to u then it is easy to see that Φ is of class $C^{1,1}$, respectively C^{k+1} , on H_0^1 . ■

1.4 Elliptic equations

Consider the linear Dirichlet boundary value problem (BVP in short)

$$\begin{cases} -\Delta u(x) = h(x) & x \in \Omega \\ u(x) = 0 & x \in \partial\Omega \end{cases} \tag{1.5}$$

where h is a given function on Ω . If $h \in L^2(\Omega)$, a weak solution of (1.5) is a function $u \in H_0^1(\Omega)$ such that

$$\int_{\Omega} \nabla u \cdot \nabla v \mathrm{d}x = \int_{\Omega} h v \mathrm{d}x, \quad \forall v \in C_0^{\infty}(\Omega).$$

Hereafter c denotes a possibly different constant independent of u .

Theorem 1.10 *Let $\Omega \subset \mathbb{R}^n$ be a bounded domain.*

(i) *If $h \in L^p(\Omega)$, $1 < p < +\infty$, then (1.5) has a unique weak solution $u \in H_0^1(\Omega) \cap H^{2,p}(\Omega)$ such that*

$$\|u\|_{H^{2,p}} \leq c \|h\|_{L^p}.$$

(ii) (Schauder estimates) If Ω is of class $C^{2,\alpha}$ and $h \in C^{0,\alpha}(\overline{\Omega})$ then $u \in C^{2,\alpha}(\overline{\Omega})$ is a classical solution of (1.5) and

$$\|u\|_{C^{2,\alpha}} \leq c\|h\|_{C^{0,\alpha}}.$$

The statement (i) of the preceding theorem allows us to define a linear selfadjoint operator $K : L^2(\Omega) \rightarrow H_0^1(\Omega)$, $h \mapsto K(h) = u$, where u denotes the unique solution of (1.5). K is the Green operator of $-\Delta$ on $H_0^1(\Omega)$. Since the embedding of $H_0^1(\Omega)$ into $L^2(\Omega)$ is compact, it follows that K is compact as a map from $L^2(\Omega)$ in itself. Similarly, we can consider K as an operator in $X = C^{0,\alpha}(\Omega)$. From (ii) of Theorem 1.10 it follows that $K(X) \subset \{u \in C^{2,\alpha}(\Omega) : u|_{\partial\Omega} = 0\}$ and Ascoli's theorem implies that K is still compact.

Remark 1.11

- (i) We point out that, here and always in the sequel, we can substitute $-\Delta$ with any uniformly elliptic second order operator with smooth coefficients and in divergence form.
- (ii) The Schauder estimates stated before hold true when $-\Delta$ is replaced by any second order uniformly elliptic operator such as

$$-\mathcal{L}u = - \sum a_{ij}(x) \frac{\partial^2 u}{\partial x_i \partial x_j} + \sum b_i(x) \frac{\partial u}{\partial x_i} + c(x)u,$$

where a_{ij}, b_i, c are of class $C^1(\overline{\Omega})$, $c \leq 0$ in $\overline{\Omega}$ and $\exists \kappa > 0$ such that $\sum a_{ij}(x)\xi_i\xi_j \geq \kappa|\xi|^2, \forall x \in \overline{\Omega}, \xi \in \mathbb{R}^n$. ■

1.4.1 Eigenvalues of linear Dirichlet boundary value problems

Consider the linear eigenvalue problem

$$\begin{cases} -\Delta u(x) = \lambda u(x) & x \in \Omega \\ u(x) = 0 & x \in \partial\Omega. \end{cases} \tag{1.6}$$

From the preceding discussion, it follows that (1.6) is equivalent to $u = \lambda K(u)$, $u \in L^2(\Omega)$ or $u \in C^{0,\alpha}(\Omega)$.

It is convenient to recall the main general properties of operators $A \in L(X)$ of the type *identity-compact*, according to the Riesz–Fredholm theory.

- (RF₁) $\text{Ker}(A)$ is finite dimensional, $\text{Range}(A)$ is closed and has finite codimension;
- (RF₂) $\text{Range}(A) = [\text{Ker}(A^*)]^\perp = \{u \in X : \langle \psi, u \rangle = 0, \forall \psi \in \text{Ker}(A^*)\}$;
- (RF₃) $\exists m \geq 1$ such that $\text{Ker}(A^k) = \text{Ker}(A^{k+1}), \forall k \geq m$. Moreover, $\forall k \geq m$ one has that $\text{Range}(A^{k+1}) = \text{Range}(A^k), X = \text{Ker}(A^m) \oplus \text{Range}(A^m)$

and the restriction of A to $\text{Range}(A^m)$ is a linear homeomorphism of $\text{Range}(A^m)$ onto itself;

(RF₄) $\text{Ker}(A) = \{0\} \iff \text{Range}(A) = X$.

The preceding results apply to $A_\lambda = I - \lambda K$, where K is the Green operator of $-\Delta$ with zero Dirichlet boundary conditions.

Definition 1.12 *A real number λ such that $\text{Ker}(A_\lambda) \neq \{0\}$ is an eigenvalue of (1.6). The integer m such that (RF₃) holds (with $A_\lambda = A$) is called the multiplicity of λ . When the multiplicity is equal to 1 we say that the eigenvalue is simple.*

The following result holds.

Theorem 1.13

(i) *Equation (1.6) has a sequence of eigenvalues λ_k such that*

$$0 < \lambda_1 < \lambda_2 \leq \lambda_3 \leq \dots, \quad \lambda_k \nearrow +\infty.$$

(Here we use the convention that multiple eigenvalues are repeated according to their multiplicity.) The first eigenvalue λ_1 is simple and the corresponding eigenfunctions do not change sign in Ω . Moreover, λ_1 is the only eigenvalue with this property.

We will denote by φ_1 the eigenfunction corresponding to λ_1 , such that $\varphi_1(x) > 0$ and $\|\varphi_1\|_{L^2} = 1$. We will also denote by φ_i the eigenfunctions corresponding to λ_i such that

$$\int_{\Omega} \varphi_h \varphi_k dx = \begin{cases} 1 & \text{if } h = k \\ 0 & \text{if } h \neq k. \end{cases}$$

(ii) *There holds*

$$\lambda_1 = \min \left\{ \int_{\Omega} |\nabla u|^2 dx : u \in H_0^1(\Omega), \int_{\Omega} u^2 dx = 1 \right\}.$$

(iii) *Letting $W_k = \{u \in H_0^1(\Omega) : \int_{\Omega} \nabla u \cdot \nabla \varphi_h dx = 0\}$ for $h = 1, \dots, k - 1$, one has that*

$$\lambda_k = \min \left\{ \int_{\Omega} |\nabla u|^2 dx : u \in W_k, \int_{\Omega} u^2 dx = 1 \right\}.$$

Properties (ii) and (iii) are the *variational characterizations* of eigenvalues, see also Section 5.5. Let us also remark that from (ii) above we can deduce a more precise form of the Poincaré inequality:

$$\lambda_1 \int_{\Omega} u^2 dx \leq \int_{\Omega} |\nabla u|^2 dx. \tag{1.7}$$

Concerning the nonhomogeneous problem

$$\begin{cases} -\Delta u(x) = \lambda u(x) + h(x) & x \in \Omega \\ u(x) = 0 & x \in \partial\Omega, \end{cases} \tag{1.8}$$

we can use the properties (RF₂)–(RF₄) to deduce the following.

Theorem 1.14

- (i) If $\lambda \neq \lambda_k$ for all integer $k \geq 1$, then (1.8) has a unique solution for any $h \in L^2(\Omega)$.
- (ii) Let λ_k be an eigenvalue of (1.6) and let V_k denote the corresponding kernel. Then, given any $h \in L^2(\Omega)$, (1.8) has a unique solution if and only if $\int_{\Omega} hv \, dx = 0$, for all $v \in V_k$.

Remark 1.15 If we work in Hölder spaces, the results stated in Theorems 1.13 and 1.14 hold with $L^2(\Omega)$ substituted by $C^{0,\alpha}(\Omega)$. ■

Let $a \in L^\infty(\Omega)$ be such that $a(x) \geq 0$ and $a(x) > 0$ in a set of positive measure in Ω . We will denote by $\lambda_k[a]$ the eigenvalues of

$$\begin{cases} -\Delta u(x) = \lambda a(x)u(x) & x \in \Omega \\ u(x) = 0 & x \in \partial\Omega. \end{cases}$$

There exist infinitely many eigenvalues $0 < \lambda_1[a] < \lambda_2[a] \leq \lambda_3[a] \leq \dots$ satisfying properties similar to those listed in Theorem 1.13. In addition, the following properties hold.

- (EP-1) (*Monotonicity property*) If $a \leq b$ then $\lambda_k[a] \geq \lambda_k[b]$, for all $k \geq 1$; moreover, if $a < b$ in a subset $\Omega' \subset \Omega$ with positive measure, then $\lambda_k[a] > \lambda_k[b]$, for all $k \geq 1$.
- (EP-2) (*Continuity property*) If $a_m \rightarrow a$ in $L^{n/2}(\Omega)$, then $\lambda_k[a_m] \rightarrow \lambda_k[a]$, for all $k \geq 1$.

1.4.2 Regularity

It is a general fact that weak solutions of the Dirichlet BVP

$$\begin{cases} -\Delta u(x) = f(x, u(x)) & x \in \Omega \\ u(x) = 0 & x \in \partial\Omega \end{cases} \tag{1.9}$$

are indeed classical solutions provided $f \in \mathbb{F}_p$ with $1 < p < (n + 2)/(n - 2)$.