

Introduction to the theory of distributions

F. G. FRIEDLANDER

*Department of Pure Mathematics and Mathematical Statistics
University of Cambridge*

with additional material by

M. Joshi

*Department of Pure Mathematics and Mathematical Statistics
University of Cambridge*

PUBLISHED BY THE PRESS SYNDICATE OF THE UNIVERSITY OF CAMBRIDGE
The Pitt Building, Trumpington Street, Cambridge CB2 1RP, United Kingdom

CAMBRIDGE UNIVERSITY PRESS

The Edinburgh Building, Cambridge CB2 2RU, UK <http://www.cup.cam.ac.uk>
40 West 20th Street, New York, NY 10011-4211, USA <http://www.cup.org>
10 Stamford Road, Oakleigh, Melbourne 3166, Australia

© Cambridge University Press 1982, 1998

This book is in copyright. Subject to statutory exception
and to the provisions of relevant collective licensing agreements,
no reproduction of any part may take place without
the written permission of Cambridge University Press.

First published 1982
Second edition 1998

Typeset in Times [vN]

A catalogue record for this book is available from the British Library

ISBN 0 521 64015 6 hardback
ISBN 0 521 64971 4 paperback

Transferred to digital printing 2003

CONTENTS

<i>Preface</i>	ix
<i>Introduction</i>	1
1 Test functions and distributions	4
1.1 Some notations and definitions	4
1.2 Test functions	5
1.3 Distributions	7
1.4 Localization	10
1.5 Convergence of distributions	13
Exercises	15
2 Differentiation, and multiplication by smooth functions	17
2.1 The derivatives of a distribution	17
2.2 Some examples	18
2.3 A distribution obtained by analytic continuation	20
2.4 Primitives in $\mathcal{D}'(\mathbf{R})$	22
2.5 Product of a distribution and a smooth function	23
2.6 Linear differential operators	25
2.7 Division in $\mathcal{D}'(\mathbf{R})$	27
2.8 Duality	29
Exercises	30
3 Distributions with compact support	34
3.1 Continuous linear forms on $C^\infty(X)$, and distributions with compact support	34
3.2 Distributions supported at the origin	36
Exercises	39
4 Tensor products	40
4.1 Test functions which depend on a parameter	40
4.2 Affine transformations	42
4.3 The tensor product of distributions	44
Exercises	48

5	Convolution	50
5.1	The convolution of two distributions	50
5.2	Regularization	53
5.3	Convolution of distributions with non-compact supports	55
5.4	Fundamental solutions of some differential operators	59
	Exercises	65
6	Distribution kernels	68
6.1	Schwartz kernels and the kernel theorem	68
6.2	Regular kernels	73
6.3	Fundamental kernels of differential operators	76
	Exercises	78
7	Coordinate transformations and pullbacks	80
7.1	Diffeomorphisms	80
7.2	The pullback of a distribution by a function	81
7.3	The wave equation on \mathbf{R}^4	85
	Exercises	88
8	Tempered distributions and Fourier transforms	90
8.1	Introduction	90
8.2	Rapidly decreasing test functions	93
8.3	Tempered distributions	96
8.4	The convolution theorem	101
8.5	Poisson's summation formula, and periodic distributions	104
8.6	The elliptic regularity theorem	108
	Exercises	110
9	Plancherel's theorem, and Sobolev spaces	114
9.1	Hilbert space	114
9.2	The Fourier transform on $L_2(\mathbf{R}^n)$	116
9.3	Sobolev spaces	120
	Exercises	126
10	The Fourier-Laplace transform	128
10.1	Analytic functions of several complex variables	128
10.2	The Paley-Wiener-Schwartz theorem	130
10.3	An application to evolution operators	134
10.4	The Malgrange-Ehrenpreis theorem	139
	Exercises	142
11	The calculus of wavefront sets	144
11.1	Definitions	144
11.2	Transformations of wavefront sets under elementary operations	148
11.3	Push-forwards and pull-backs	154
11.4	Wavefront sets and Schwartz kernels	157
11.5	Propagation of singularities	159
	Exercises	160

<i>Contents</i>	<i>vii</i>
<i>Appendix: topological vector spaces</i>	162
<i>Bibliography</i>	170
<i>Notation</i>	171
<i>Index</i>	173

INTRODUCTION

The theory of distributions is a generalization of classical analysis, which makes it possible to deal in a systematic manner with difficulties which previously had been overcome by *ad hoc* constructions, or just by pure hand waving. In fact, it does a good deal more: it provides a new and wider framework, and a more perspicuous language, in which one can reformulate and develop classical problems. Its influence has been particularly pervasive and fruitful in the theory of linear partial differential equations.

Let us consider some examples. If $(x, t) \in \mathbf{R}^2$, then

$$u = f(x + t) + g(x - t)$$

satisfies d'Alembert's equation

$$\frac{\partial^2 u}{\partial t^2} - \frac{\partial^2 u}{\partial x^2} = 0,$$

provided that the functions f and g are twice differentiable. This restriction is both irksome and unnatural in many instances. It can be overcome by introducing so-called weak solutions. By definition, these are functions u such that

$$\int u \left(\frac{\partial^2 \phi}{\partial t^2} - \frac{\partial^2 \phi}{\partial x^2} \right) dx dt = 0$$

for all sufficiently 'good' functions ϕ , for example for $\phi \in C_c^2(\mathbf{R}^2)$, the class of twice continuously differentiable functions that vanish on the exterior of a bounded set.

Again, if $x \in \mathbf{R}^3$, then the Newtonian potential

$$u(x) = \int \frac{f(y)}{|x - y|} dy$$

satisfies Poisson's equation

$$\Delta u = -4\pi f$$

if the density function f is, for example, continuously differentiable. But it may not possess second order derivatives when f is merely continuous. Yet, it is then

continuously differentiable and obeys Gauss's law that the flux of the field across a closed surface S is proportional to the matter enclosed by S . This difficulty can also be avoided by working with weak solutions of Poisson's equation. Furthermore, if one replaces f by the Dirac delta 'function', one obtains $u = 1/|x| = (x_1^2 + x_2^2 + x_3^2)^{-1/2}$ when $x \neq 0$, which is the potential due to a particle at the origin. It is suggestive to express this by writing

$$\Delta(1/|x|) = -4\pi\delta(x).$$

But this has to be interpreted; for example, one can take it to mean that

$$\int \frac{\Delta\phi(x)}{|x|} dx = -4\pi\phi(0)$$

for all 'good' functions, say for all $\phi \in C_c^2(\mathbf{R}^3)$.

In all these cases, the difficulties and ambiguities disappear when the equations are read in terms of distributions. In the theory of distributions, functions are replaced by linear forms on an auxiliary vector space, whose members are called test functions. Recall that, if V is a vector space over the field \mathbf{C} of complex numbers, then a linear form on V is a homomorphism $V \rightarrow \mathbf{C}$. The linear forms on V are made into a vector space $\text{Hom}(V, \mathbf{C})$ in the obvious way: $\langle cu, \phi \rangle = c\langle u, \phi \rangle$ if $c \in \mathbf{C}$ and $u \in \text{Hom}(V, \mathbf{C})$, and $\langle u + v, \phi \rangle = \langle u, \phi \rangle + \langle v, \phi \rangle$ if $u, v \in \text{Hom}(V, \mathbf{C})$, where $\phi \in V$ in each case. In distribution theory, the basic space of test functions is $C_c^\infty(\mathbf{R}^n)$; its members are (complex valued) functions on \mathbf{R}^n which possess continuous derivatives of all orders, and vanish outside some bounded set. The notations $C_0^\infty(\mathbf{R}^n)$, and L. Schwartz's original $\mathcal{D}(\mathbf{R}^n)$, are also used.

A continuous function $f: \mathbf{R}^n \rightarrow \mathbf{C}$ determines a linear form on $C_c^\infty(\mathbf{R}^n)$ by the rule

$$\langle f, \phi \rangle = \int_{\mathbf{R}^n} f\phi dx, \quad \phi \in C_c^\infty(\mathbf{R}^n). \quad (1)$$

Conversely, it can (and will) be shown that this linear form determines f uniquely so that the space of continuous functions on \mathbf{R}^n can be identified with a subspace of $\text{Hom}(C_c^\infty(\mathbf{R}^n), \mathbf{C})$. If the function f is also continuously differentiable, then the linear forms on $C_c^\infty(\mathbf{R}^n)$ determined by its derivatives are, by (1) and an integration by parts,

$$\langle \partial f / \partial x_i, \phi \rangle = \int \phi(\partial f / \partial x_i) dx = - \int f(\partial \phi / \partial x_i) dx,$$

$$i = 1, \dots, n, \phi \in C_c^\infty(\mathbf{R}^n).$$

Thus, for $i = 1, \dots, n$,

$$\langle \partial f / \partial x_i, \phi \rangle = - \langle f, \partial \phi / \partial x_i \rangle, \quad \phi \in C_c^\infty(\mathbf{R}^n). \quad (2)$$

But this makes sense for any linear form on $C_c^\infty(\mathbf{R}^n)$, and so provides a definition of the derivatives of such a form. As one can iterate (2), one thus obtains (generalized) derivatives of all orders.

Multiplication by smooth (infinitely differentiable) functions can also be defined by analogy with the special case (1); one simply puts

$$\langle fu, \phi \rangle = \langle u, f\phi \rangle, \quad \phi \in C_c^\infty(\mathbf{R}^n). \quad (3)$$

By combining (2) and (3), one can thus account for the action of any linear differential operator with smooth coefficients on $\text{Hom}(C_c^\infty(\mathbf{R}^n), \mathbf{C})$.

There is one other essential ingredient. The class of distributions is not the whole of $\text{Hom}(C_c^\infty(\mathbf{R}^n), \mathbf{C})$: it is the subspace consisting of continuous linear forms. To say this, presupposes that $C_c^\infty(\mathbf{R}^n)$ has been equipped with an appropriate topology. The choice of this topology is, in fact, a cardinal feature of the theory of distributions. To define it, and to explore its implications, one must appeal to the theory of locally convex topological vector spaces. However, the course adopted in this book is to specify a certain set of inequalities which a linear form on $C_c^\infty(\mathbf{R}^n)$ must satisfy in order to qualify as a distribution.

Once these are granted, the theory can be built up systematically and logically. But, so as to give some idea of what is involved, to readers who either do not have the time, or the inclination, to go into this more fully, a sketch of the functional-analytic background is given as an Appendix at the end of the book. This can be omitted, and the reader who does so should also ignore references to topological vector spaces in the text.