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978-0-521-58401-2 - Control Theory for Partial Differential Equations: Continuous and Approximation Theories, Volume II - Abstract Hyperbolic-like Systems over a Finite Time Horizon

Irena Lasiecka and Roberto Triggiani

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7

Some Auxiliary Results on Abstract Equations

In the present chapter we collect, in Sections 7.1 through 7.5, a number of results that will be invoked repeatedly throughout the present volume as well as Volume III. They concern (1) regularity results of the input \rightarrow solution map, and its adjoint map, over both a finite or an infinite time interval and (2) generation and abstract trace regularity under unbounded perturbation. In addition, in Section 7.6, we provide an abstract regularity result for damped second-order equations of interest in itself. Illustrations thereof are given in Section 7.7 and in Chapter 9, Section 9.10.4.

7.1 Mathematical Setting and Standing Assumptions

Throughout this chapter X and U are reflexive Banach spaces and X^* and U^* are their dual spaces. For a given $0 < T < \infty$ fixed, we shall study the operator L ,

$$(Lu)(t) = \int_0^t e^{A(t-\tau)} Bu(\tau) d\tau, \quad 0 \leq t \leq T, \quad (7.1.1)$$

corresponding to the mild solution

$$x(t) = e^{At}x_0 + (Lu)(t) \quad (7.1.2)$$

of the abstract equation

$$\dot{x} = Ax + Bu \in [\mathcal{D}(A^*)]', \quad x(0) = x_0, \quad (7.1.3)$$

subject to the following standing assumptions:

- (H.1) $A : X \supset \mathcal{D}(A) \rightarrow X$ is a linear operator, which is the infinitesimal generator of a strongly continuous (s.c.) semigroup e^{At} on X .
- (H.2) B is a linear, continuous operator $U \rightarrow [\mathcal{D}(A^*)]'$, where A^* is the X -adjoint of A , and $[\mathcal{D}(A^*)]'$ is the dual of $\mathcal{D}(A^*)$ with respect to the pivot space X , or equivalently,

$$A^{-1}B \in \mathcal{L}(U; X). \quad (7.1.4a)$$

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For considerations of L , over a finite time interval, we may assume, without loss of generality, that $A^{-1} \in \mathcal{L}(X)$, for otherwise we replace (7.1.4a) with

$$(\lambda_0 I - A)^{-1} B \in \mathcal{L}(U; X), \quad \lambda_0 \in \text{resolvent set } \rho(A). \quad (7.1.4b)$$

(H.3) (Abstract trace regularity) Given $0 < T < \infty$ and $1 \leq q \leq \infty$, there exists a constant $C_T > 0$ [which depends on T and on q , but dependence on q is omitted], such that

$$\begin{cases} \int_0^T \|B^* e^{A^* t} x^*\|_{U^*}^q dt \leq C_T \|x^*\|_{X^*}^q, & x^* \in \mathcal{D}(A^*), \quad 1 \leq q < \infty; \\ \|B^* e^{A^* t} x^*\|_{L_\infty(0,T;U^*)} \leq C_T \|x^*\|_{X^*}, & x^* \in \mathcal{D}(A^*), \quad q = \infty, \end{cases} \quad (7.1.5a)$$

so that the closable (cf. Remark 7.1.1 below) operator $B^* e^{A^* t}$ admits a continuous extension (which may then be denoted by the same symbol) satisfying

$$B^* e^{A^* t} : \text{continuous } X^* \rightarrow L_q(0, T; U^*), \quad 1 \leq q \leq \infty, \quad (7.1.5b)$$

that is,

$$\begin{cases} \int_0^T \|B^* e^{A^* t} x^*\|_{U^*}^q dt \leq C_T \|x^*\|_{X^*}^q, & x^* \in X^*, \quad 1 \leq q < \infty; \\ \|B^* e^{A^* t} x^*\|_{L_\infty(0,T;U^*)} \leq C_T \|x^*\|_{X^*}, & x^* \in X^*, \quad q = \infty. \end{cases} \quad (7.1.5c)$$

Here B^* , the dual of B , satisfies $B^* \in \mathcal{L}(\mathcal{D}(A^*); U^*)$, after identifying $[\mathcal{D}(A^*)]'$ with $\mathcal{D}(A^*)$. Moreover, $e^{A^* t}$ is a s.c. semigroup on X^* .

Remark 7.1.1 By a change of variable and use of the semigroup property, if (7.1.5) holds for one fixed $0 < T < \infty$, then (7.1.5) holds for $2T, 3T, \dots$, hence for any $0 < T < \infty$.

Remark 7.1.2 The original s.c. semigroup e^{At} on X of assumption (H.1) can always be extended as a s.c. semigroup on the extrapolation space $[\mathcal{D}(A^*)]'$. We shall continue to use the notation e^{At} for such an extension. Moreover, solely under (H.1) and (H.2), it is plainly always the case that

$$L : \text{continuous } L_p(0, T; U) \rightarrow C([0, T]; [\mathcal{D}(A^*)]'), \quad 1 \leq p \leq \infty. \quad (7.1.6)$$

Remark 7.1.3 Under (H.1) and (H.2), if $u \in H^1(0, T; U)$, then formula (7.1.1) for L yields, after integration by parts,

$$\begin{aligned} (Lu)(t) &= - \int_0^t \frac{de^{A(t-\tau)}}{d\tau} A^{-1} Bu(\tau) d\tau \\ &= e^{At} A^{-1} Bu(0) - A^{-1} Bu(t) + \int_0^t e^{A(t-\tau)} A^{-1} B \dot{u}(\tau) d\tau \\ &\in C([0, T]; X). \end{aligned} \quad (7.1.7)$$

The above computations are justified on the extrapolation space $[\mathcal{D}(A^*)]'$, via Remark 7.1.2. However, the final result lies in X , at least for $u \in H^1(0, T; U)$, as noted in (7.1.7). Thus, (7.1.7) says, in particular, that the operator

$$L_T u = \int_0^T e^{A(T-t)} B u(t) dt = A \int_0^T e^{A(T-t)} A^{-1} B u(t) dt \quad (7.1.8)$$

is densely defined as an operator $L_p(0, T; U) \supset \mathcal{D}(L_T) \rightarrow X$, $1 \leq p \leq \infty$. Moreover, L_T – being in (7.1.8) (right) the composition of a closed boundedly invertible operator A with a bounded operator – is closed [Kato, 1966, p. 164]. An adjoint of L_T is:

$$(Sx^*)(t) = B^* e^{A^* t} x^*, \quad x^* \in \mathcal{D}(S), \quad 0 \leq t \leq T, \quad \text{a.e.}, \quad (7.1.9a)$$

which is closable [Kato, 1966, p. 168] as an operator $X^* \supset \mathcal{D}(S) \rightarrow L_q(0, T; U^*)$, $1 \leq q \leq \infty$, as noted above (7.1.5b), where $1/p + 1/q = 1$. The unique maximal extension of the operator in (7.1.9a), which is mentioned in assumption (H.3) above, is the adjoint L_T^* of L_T . Since L_T in (7.1.8) is densely defined and closed, then $(L_T^*)^* = L_T$. Thus, hypothesis (H.3) = (7.1.5b) is now paraphrased by saying

$$(L_T^* x^*)(t) = B^* e^{A^* t} x^* : \text{continuous } X^* \rightarrow L_q(0, T; U^*), \quad (7.1.9b)$$

or equivalently for $1 \leq q < \infty$, and a fortiori for $q = \infty$:

(H.3*)

$$L_T : \text{continuous } L_p(0, T; U) \rightarrow X, \quad 1 \leq p \leq \infty, \quad \frac{1}{p} + \frac{1}{q} = 1. \quad (7.1.10)$$

The point is that, although the extrapolation space $[\mathcal{D}(A^*)]'$ acts as an all-encompassing, backup space for the regularity of L , and for performing computations, solely under (H.1) and (H.2), according to (7.1.7), L may be more regular. Indeed, more precisely, we have that

$$L : \text{continuous } L_p(0, T; U) \rightarrow C([0, T]; X), \quad (7.1.11)$$

with $1 \leq p < \infty$, if and only if (H.3) holds true with $1 < q \leq \infty$, or, with $p = \infty$, provided that (H.3) holds true with $q = 1$. This is the content of Theorem 7.2.1 below.

Remark 7.1.4 We note explicitly that, if there exists a point T , $0 < T < \infty$, such that

$$L_T u = \int_0^T e^{A(T-\tau)} B u(\tau) d\tau \in X, \quad \forall u \in L_2(0, T; U), \quad (7.1.12)$$

then, for all $0 < t_1 < T$, we likewise have

$$L_{t_1} u = \int_0^{t_1} e^{A(t_1-\tau)} B u(\tau) d\tau \in X, \quad \forall u \in L_2(0, t_1; U). \quad (7.1.13)$$

Indeed, choosing at first u smooth, say $u \in C([0, T]; U)$, we write for any $0 < t < T$:

$$L_T u = \int_0^t e^{A(T-\tau)} B u(\tau) d\tau + \int_t^T e^{A(T-\tau)} B u(\tau) d\tau \tag{7.1.14}$$

$$= \int_0^T e^{A(T-\tau)} B u_{\text{ext}}(\tau) d\tau + \int_0^{T-t} e^{A(T-t-\sigma)} B u_t(\sigma) d\sigma, \tag{7.1.15}$$

where $u_{\text{ext}}(\tau)$ extends by zero $u(\tau)$ for $t < \tau \leq T$ in the first integral, whereas in the second integral we set $u_t = u(t + \sigma)$, $\tau - t = \sigma$. Extending u to all $u \in L_2(0, T; U)$ and setting $t_1 = T - t$, we obtain, by assumption (1.12),

$$L_{t_1} u_t = L_T u - L_T u_{\text{ext}} \in Y, \quad \forall u \in L_2(0, T_1; U), \tag{7.1.16}$$

as desired, and (7.1.13) is established.

7.2 Regularity of L and L^* on $[0, T]$

As anticipated at the end of Remark 7.1.3, the “trace” regularity (H.3) = (7.1.5) of L_T^* , equivalently the final state “interior” regularity (H.3*) = (7.1.10) of L_T , is equivalent to the following “interior” regularity for L .

Theorem 7.2.1 Assume (H.1) and (H.2).

(i) For $1 < q \leq \infty$ [respectively, $q = 1$], hypothesis (H.3) is equivalent to [respectively, implies] the following regularity property of the operator L in (7.1.1):

$$L : \text{continuous } L_p(0, T; U) \rightarrow C([0, T]; X), \quad 1 \leq p \leq \infty, \tag{7.2.1a}$$

that is, there exists $k_T > 0$ such that

$$\|Lu\|_{C([0, T]; X)} \leq k_T \|u\|_{L_p(0, T; U)}. \tag{7.2.1b}$$

(ii) For $1 \leq q \leq \infty$, hypothesis (H.3) implies that the adjoint operator L^* satisfies

$$(L^*v)(t) = \int_t^T B^* e^{A^*(\tau-t)} v(\tau) d\tau \tag{7.2.2a}$$

$$: \text{continuous } L_1(0, T; X^*) \rightarrow L_q(0, T; U^*). \tag{7.2.2b}$$

The operator L^* is the adjoint of L in the sense that, with $1/p + 1/q = 1$,

$$(Lu, v)_{p, X; q, X^*} = (u, L^*v)_{p, U; q, U^*}, \tag{7.2.3}$$

where the notation on the left and on the right of (7.2.3) denotes, respectively, the duality pairing between $L_p(0, T; X)$ and $L_q(0, T; X^*)$, and between $L_p(0, T; U)$ and $L_q(0, T; U^*)$.

Proof.

(i) **Step 1** We first prove that, under (H.1) and (H.2), assumption (H.3) = (7.1.5) for $1 \leq q \leq \infty$ implies that

$$L : \text{continuous } L_p(0, T; U) \rightarrow L_\infty(0, T; X). \tag{7.2.4}$$

To this end, with $v \in L_1(0, T; X^*)$ and $u \in L_p(0, T; U)$, we compute from (7.2.3) and (7.1.1), with $1 < p < \infty$: To this end, with $v \in L_1(0, T; X^*)$ and $u \in L_p(0, T; U)$, we compute from (7.2.3) and (7.1.1), with $1 < p < \infty$:

$$\begin{aligned} |(Lu, v)_{\infty, X; 1, X^*}| &= \left| \int_0^T ((Lu)(t), v(t)) dt \right| \\ &= \left| \int_0^T \int_0^t (u(\tau), B^* e^{A^*(t-\tau)} v(t)) d\tau dt \right| \\ (t - \tau = \sigma) \quad &\leq \int_0^T \left\{ \int_0^t \|u(\tau)\|_U^p d\tau \right\}^{\frac{1}{p}} \left\{ \int_0^t \|B^* e^{A^*\sigma} v(t)\|_{X^*}^q d\sigma \right\}^{\frac{1}{q}} dt \end{aligned}$$

(replacing t with T in both integral signs, and using (H.3) = (7.1.5c))

$$\begin{aligned} &\leq \|u\|_{L_p(0, T; U)} \int_0^T C_T \|v(t)\|_{X^*} dt \\ &= C_T \|u\|_{L_p(0, T; U)} \|v\|_{L_1(0, T; X^*)}. \end{aligned} \tag{7.2.5}$$

[In the above estimates, either one considers $v(t) \in X^*$ a.e. or one takes $v(t) \in C([0, T]; X^*)$ and extends estimate (7.2.5) to all of $v \in L_1(0, T; X^*)$.] An obvious variation leads likewise to (7.2.5) also for $p = \infty$, or $q = \infty$. Then (7.2.4) is established for $1 \leq q \leq \infty$.

Step 2 Let $u \in L_p(0, T; U)$. By taking now u_n smooth, say $u_n \in C^1([0, T]; U)$, with $u_n \rightarrow u$ in $L_p(0, T; U)$, and integrating $(Lu_n)(t)$ by parts as in (7.1.7), we then see that $(Lu_n)(t) \in C([0, T]; X)$ by (7.1.7), whereas $Lu_n \rightarrow Lu$ in $L_\infty(0, T; X)$ by (7.2.4), and thus $Lu \in C([0, T]; X)$. The continuity of L in (7.2.4) is then improved to the continuity of L in (7.2.1), as desired.

Step 3 Conversely, the continuity of L in (7.2.1) implies the continuity of L_T in (7.1.10), and hence, equivalently for $1 \leq p < \infty$, the continuity of L_T^* defined by (7.1.9) given by (H.3) = (7.1.5b).

(ii) Statement (7.2.2b) follows from (7.2.1) by duality. \square

Remark 7.2.1 In application to partial differential equations in this volume we shall use Theorem 7.2.1 in the Hilbert space setting, with $X = X^*$ and $U = U^*$ Hilbert spaces, and $p = q = 2$.

Remark 7.2.2 The conclusion of Theorem 7.2.1 for L applies also to the operator

$$u \rightarrow \int_t^T e^{A(\tau-t)} Bu(\tau) d\tau, \tag{7.2.6}$$

as we shall need, for example, in Chapters 8 and 9. Similarly, at times, as in the forthcoming Chapter 8, Section 8.2.1, we shall start with the assumption

$$Re^{At} B : \text{continuous } U \rightarrow L_q(0, T; Z), \tag{7.2.7}$$

for A and B as in (H.1) and (H.2) = (7.1.4), and with R a suitable operator $R \in \mathcal{L}(Y; Z)$ and U and Z Hilbert spaces [the case $q = 1$ will be relevant]. Then, a variation of the proof of Theorem 7.2.1 yields: For $1 < q \leq \infty$ [respectively, for $q = 1$], property (7.2.7) is equivalent to [respectively, implies] the following property:

$$(L^* R^* f)(t) = \int_t^T B^* e^{A^*(\tau-t)} R^* f(\tau) d\tau \tag{7.2.8a}$$

$$: \text{continuous } L_p(0, T; Z) \rightarrow C([0, T]; U), \tag{7.2.8b}$$

where $1/p + 1/q = 1$. Indeed, the counterpart of Step 1 in (7.2.5) is now, by (7.2.8a), for $f \in L_p(0, T; Z)$, $1 \leq p < \infty$, $g \in L_1(0, T; U)$,

$$\begin{aligned} |(L^* R^* f, g)_{\infty, U; 1, U}| &= \left| \int_0^T \int_t^T (f(\tau), Re^{A(\tau-t)} Bg(t))_Z d\tau dt \right| \\ &\leq \int_0^T \left\{ \int_t^T \|f(\tau)\|_Z^p d\tau \right\}^{\frac{1}{p}} \left\{ \int_t^T \|Re^{A(\tau-t)} Bg(t)\|_Z^q d\tau \right\}^{\frac{1}{q}} dt \\ \text{(by (7.2.7))} &\leq \|f\|_{L_p(0, T; Z)} \int_0^T C_T \|g(t)\|_U dt \\ &= C_T \|f\|_{L_p(0, T; Z)} \|g\|_{L_1(0, T; U)}. \end{aligned} \tag{7.2.9}$$

An obvious variation leads likewise to (7.2.9) also for $p = \infty$. Thus, (7.2.9) says that

$$L^* R^* : \text{continuous } L_p(0, T; Z) \rightarrow L_\infty(0, T; U). \tag{7.2.10}$$

Next, the $L_\infty(0, T; U)$ -regularity in (7.2.10) is lifted up to the $C([0, T]; U)$ -regularity in (7.2.8b), by an approximation argument, as in Step 2, above.

First, if $f \in H^1(0, T; Z)$, then integration by parts on (7.2.8a) yields only under (H.1) and (H.2):

$$(L^* R^* f)(t) = \int_t^T B^* A^{*-1} \frac{de^{A^*(\tau-t)}}{d\tau} R^* f(\tau) d\tau \tag{7.2.11}$$

$$\begin{aligned} &= B^* A^{*-1} e^{A^*(T-t)} R^* f(T) - B^* A^{*-1} R^* f(t) \\ &\quad - \int_t^T B^* A^{*-1} e^{A^*(\tau-t)} R^* \dot{f}(\tau) d\tau \in C([0, T]; U). \end{aligned} \tag{7.2.12}$$

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Next, let $f \in L_p(0, T; Z)$. By taking now f_n smooth, say $f_n \in C^1([0, T]; Z)$, with $f_n \rightarrow f$ in $L_p(0, T; Z)$, we then see that $L^*R^*f_n \in C([0, T]; U)$ by (7.2.12), whereas $L^*R^*f_n \rightarrow L^*R^*f$ in $L_\infty(0, T; Z)$ by (7.2.10), and thus $L^*R^*f \in C([0, T]; Z)$, as desired.

7.3 A Lifting Regularity Property When e^{At} Is a Group

Under assumptions (H.1) and (H.2) and, moreover, with e^{At} a group, the next result lifts the time regularity from L_p to C , while preserving the same space regularity. For the classes of PDEs, we have in mind, and for which the original hypothesis (7.3.1) applies, the assumption that e^{At} is a group is automatically satisfied. The result is false for general semigroups; see Remark 7.3.1.

Theorem 7.3.1 *Assume (H.1) and (H.2), and, moreover, that $G(t) = e^{At}$ is a s.c. group. Furthermore, suppose that the operator L in (7.1.1) satisfies*

$$L : \text{continuous } L_p(0, T; U) \rightarrow L_p(0, T; X), \quad 1 \leq p < \infty. \quad (7.3.1)$$

Then, in fact, property (H.3) = (7.1.5) holds true, and then

$$L : \text{continuous } L_p(0, T; U) \rightarrow C([0, T]; X). \quad (7.3.2)$$

Proof. By duality on (7.3.1) we obtain that the operator L^* in (7.2.2a) satisfies, with $1/p + 1/q = 1$:

$$L^* : \text{continuous } L_q(0, T; X^*) \rightarrow L_q(0, T; U^*). \quad (7.3.3)$$

We now use the group assumption on e^{At} and apply L^* to a *special* function, given by the dual free ($B \equiv 0$) dynamics of (7.1.3), backward in time, that is, to

$$\hat{f}(\tau) = e^{A^*(-\tau)}x^* \in L_q(0, T; X^*), \quad x^* \in X^*. \quad (7.3.4)$$

Then, from (7.2.2), we obtain

$$\begin{aligned} (L^*\hat{f})(t) &= \int_t^T B^*e^{A^*(\tau-t)}e^{A^*(-\tau)}x^* d\tau \\ &= (T-t)B^*e^{A^*(-t)}x^* \in L_q(0, T; U^*), \end{aligned} \quad (7.3.5)$$

recalling (7.3.3), and hence $B^*e^{A^*(-t)}x^* \in L_q(0, T - \epsilon; U^*)$, for any $0 < \epsilon < T$. Since this conclusion holds true for any finite T and any $\epsilon > 0$ small (recall Remark 7.1.1), we then obtain that

$$B^*e^{A^*(-t)}x^* \in L_q(0, T; U^*), \quad x^* \in X^*, \quad (7.3.6)$$

continuously; that is, writing $x^* = e^{A^*T}y^*$, or $y^* = e^{A^*(-T)}x^* \in X^*$, we have from (7.3.6)

$$B^*e^{A^*(T-t)} : \text{continuous } X^* \rightarrow L_q(0, T; U^*), \quad (7.3.7)$$

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which is (H.3) = (7.1.5c), as desired. The equivalence between (H.3) and (7.3.3) noted in Theorem 7.2.1(i) completes the proof. \square

Remark 7.3.1 The lifting regularity result of Theorem 7.3.1 can be applied to mixed problems for second-order hyperbolic equations, for Euler–Bernoulli equations, for Kirchoff equations, etc.; see Lasiecka and Triggiani [1983; 1991]. A few applications will be made in Chapter 9, Section 9.8 in the study of the regularity of wave and Kirchoff equations with interior point control.

Remark 7.3.2 The assumption that e^{At} be a s.c. group is crucial in the above theorem, in the sense that if e^{At} is only a s.c. semigroup even if holomorphic, the conclusion of the theorem is false. As an example illustrating this, let $y(t, x)$ be the solution of a corresponding parabolic equation with, say, zero initial condition and with forcing term u in the Dirichlet boundary conditions,

$$\begin{cases} y_t = \Delta y, & \text{in } (0, T] \times \Omega = Q_T; \\ y(0, \cdot) = 0, & \text{in } \Omega; \\ y|_{\Sigma_T} = u, & \text{in } (0, T] \times \Gamma = \Sigma_T, \end{cases} \quad (7.3.8)$$

as in Chapter 3. Then the corresponding free solution ($u \equiv 0$) is described by a s.c., holomorphic semigroup on $L_2(\Omega)$ (which therefore is not a group). We have that the map $u \rightarrow y$ is continuous from $L_2(\Sigma_T) \rightarrow L_2(Q_T)$ (even $L_2(\Sigma_T) \rightarrow L_2(0, T; H^{\frac{1}{2}}(\Omega))$), see Chapter 3, Section 3.1, yet the map $u \rightarrow y(T)$ from $L_2(\Sigma_T)$ to $L_2(\Omega)$ is not continuous. In fact, for a preassigned $0 < T < \infty$, one may construct $u \in L_2(\Sigma_T)$ whose corresponding solution y satisfies $y(T) \notin L_2(\Omega)$ [Lions, 1971, p. 202], even in the one-dimensional case.

Remark 7.3.3 The above proof extends almost verbatim to other settings as well. For instance, one may replace assumption (7.3.1) by

$$L : \text{continuous } H^1(0, T; U) \rightarrow L_2(0, T; X), \quad (7.3.9)$$

$U = U^*$, $X = X^*$ (Hilbert spaces), and then the conclusion (7.3.2) becomes

$$L : \text{continuous } H^1(0, T; U) \rightarrow C([0, T]; X). \quad (7.3.10)$$

We shall not need these settings, however.

Proof of implication. (7.3.9) \Rightarrow (7.3.10). Under assumption (7.3.9), the counterparts of (7.3.6) and (7.3.7) are now

$$B^* e^{A^*(-t)} x \in [H^1(0, T; U)]' \quad (7.3.11)$$

continuously in $x \in X$, and

$$B^* e^{A^*(T-t)} : \text{continuous } X \rightarrow [H^1(0, T; U)]', \quad (7.3.12)$$

respectively, where $[H^1(0, T; U)]'$ is the dual of $H^1(0, T; U)$ with respect to

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7.4 Extension of Regularity of L and L^* on $[0, \infty]$ When e^{At} Is Uniformly Stable 653

$L_2(0, T; U)$ as a pivot space. From here, it follows that

$$L_T u = \int_0^T e^{A(T-t)} B u(t) dt : \text{continuous } H^1(0, T; U) \rightarrow X. \tag{7.3.13}$$

Finally, with $v \in L_1(0, T; X)$ and $u \in H^1(0, T; U)$, one obtains

$$\begin{aligned} \int_0^T (Lu)(t), v(t) \rangle_X dt &= \int_0^T \left(\int_0^t e^{A(t-\tau)} B u(\tau) d\tau, v(t) \right) dt \\ &= \int_0^T \int_0^t (u(\tau), B^* e^{A^*(t-\tau)} v(t))_U d\tau dt \end{aligned} \tag{7.3.14}$$

$$\leq \int_0^T \|u\|_{H^1(0,t;U)} \|B^* e^{A^*(t-\tau)} v(t)\|_{[H^1(0,t;U)]'} dt \tag{7.3.15}$$

$$\text{(by (7.3.12))} \leq \int_0^T \|u\|_{H^1(0,T;U)} c_t \|v(t)\|_X dt \tag{7.3.16}$$

$$\leq c_T \|u\|_{H^1(0,T;U)} \int_0^T \|v(t)\|_X dt, \tag{7.3.17}$$

as desired, which is the counterpart of (7.2.5). In going from (7.3.15) to (7.3.16), we have recalled (7.3.12) and used that $c_t \leq c_T$ for all $t \leq T$, by duality on the original assumption (7.3.10). Then (7.3.17) yields conclusion (7.3.10) as desired, by an approximation argument, as in Step 2 in the proof of Theorem 7.2.1.

7.4 Extension of Regularity of L and L^* on $[0, \infty]$ When e^{At} Is Uniformly Stable

In this section, in addition to (H.1), (H.2), and (H.3), we assume the following ‘‘uniform exponential stability’’ property of e^{At} , that is, stability in the uniform operator topology:

(H.4) There exist constants $M \geq 1, \omega > 0$, such that

$$\|e^{At}\|_{\mathcal{L}(X)} \leq M e^{-\omega t}, \quad t \geq 0. \tag{7.4.1}$$

As a consequence of (H.4), we extend the continuity of the operator L in (7.1.1) from $T < \infty$ to $T = \infty$. We shall provide a direct statement and a direct proof in Section 7.4.1 and a dual statement and a dual proof in Section 7.4.2.

7.4.1 Direct Statement; Direct Proof

Theorem 7.4.1.1 Assume (H.1), (H.2), (H.3) = (7.1.5), and (H.4) = (7.4.1). Let $1 \leq p < \infty$. Let $\epsilon > 0$ be such that

$$-\omega + \epsilon < 0, \tag{7.4.1.1}$$

with ω the constant in (7.4.1). Then hypothesis (H.3), in its version given by (7.2.1), that is, $L: \text{continuous } L_p(0, T; U) \rightarrow C([0, T]; X)$, $1 \leq p < \infty$, can be improved to the following statements:

$$e^{\epsilon t} L : \text{continuous } L_p(0, \infty; U) \rightarrow L_p(0, \infty; X) \tag{7.4.1.2}$$

$$: \text{continuous } L_p(0, \infty; U) \rightarrow C([0, \infty]; X), \tag{7.4.1.3}$$

where the latter is the space of X -valued continuous functions bounded on $[0, \infty]$, that is, bounded under the sup norm.

Proof. Proof of (7.4.1.2). We first prove (7.4.1.2) for $\epsilon = 0$. We let $f(t) = \|(Lu)(t)\|_X^p$ for $u \in L_p(0, \infty; U)$ and obtain

$$\begin{aligned} \int_0^\infty \|(Lu)(t)\|_X^p dt &= \int_0^\infty f(t) dt = \sum_{n=0}^\infty \int_{nT}^{(n+1)T} f(t) dt \\ &= \sum_{n=0}^\infty \int_0^T f(nT + t) dt. \end{aligned} \tag{7.4.1.4}$$

By splitting the interval $[0, nT + t]$ in $[0, T]$, $[T, 2T]$, etc., and with a change of variable, we compute for $n = 1, 2, \dots$, via (7.1.1) and the semigroup property

$$\begin{aligned} f(nT + t) &= \|(Lu)(nT + t)\|_X^p = \left\| \int_0^{nT+t} e^{A(nT+t-\tau)} Bu(\tau) d\tau \right\|_X^p \\ &= \left\| \sum_{j=1}^n e^{A((n-j)T+t)} \int_0^T e^{A(T-\tau)} Bu((j-1)T + \tau) d\tau \right. \\ &\quad \left. + \int_0^t e^{A(t-\tau)} Bu(nT + \tau) d\tau \right\|_X^p. \end{aligned} \tag{7.4.1.5}$$

Using the assumed stability (7.4.1) = (H.4) and the continuity (7.2.1b), which is equivalent to (H.3), we get

$$\begin{aligned} f(nT + t) &\leq k_T^p \left\{ M e^{-\omega t} \sum_{j=1}^n e^{-\omega(n-j)T} \left(\int_0^T \|u((j-1)T + \tau)\|_U^p d\tau \right)^{\frac{1}{p}} \right. \\ &\quad \left. + \left(\int_0^T \|u(nT + \tau)\|_U^p d\tau \right)^{\frac{1}{p}} \right\}^p \\ &\leq k_T^p c_p \left\{ M^p e^{-\omega t} \left(\sum_{j=1}^n e^{-\omega(n-j)T} \|u\|_{L_p((j-1)T, jT; U)} \right)^p \right. \\ &\quad \left. + \|u\|_{L_p(nT, (n+1)T; U)}^p \right\}, \end{aligned} \tag{7.4.1.6}$$