

CONTENTS

Preface	viii
1 First-order autonomous systems	1
1.1 Basic theory	1
1.2 Rotation	6
1.3 Natural boundaries	7
1.4 Examples from biology	8
<i>Exercises</i>	9
2 Linear transformations of the plane	12
2.1 Introduction	12
2.2 Area-preserving transformations	13
2.3 Transformations with dilation	18
<i>Exercises</i>	21
3 Second-order autonomous systems	23
3.1 Systems of order n	23
3.2 Phase flows of second-order autonomous systems	25
3.3 Fixed points, equilibrium and stability	26
3.4 Separation of variables	28
3.5 Classification of fixed points	32
3.6 Summary of classification	34
3.7 Determination of fixed points	36
3.8 Limit cycles	37
<i>Exercises</i>	38
4 Conservative Hamiltonian systems of one degree of freedom	42
4.1 Newtonian and Hamiltonian systems	42
4.2 Conservative systems	44
4.3 Linear conservative systems	45
4.4 The cubic potential	49
4.5 General potential	51
4.6 Free rotations	53
4.7 The vertical pendulum	54
4.8 Rotation, libration and periods	56
4.9 Area-preserving flows and Liouville's theorem	57
<i>Exercises</i>	60

Contents

5 Lagrangians	66
5.1 Introduction	66
5.2 The Legendre transformation	67
5.3 The Lagrangian equation of motion	70
5.4 Formulation	72
<i>Exercises</i>	78
6 Transformation theory	84
6.1 Introduction	84
6.2 The theory of time-independent transformations	84
6.3 The $F_1(Q, q)$ generating function	87
6.4 Other forms of generating function	89
6.5 The transformed Hamiltonian	92
6.6 Time-dependent transformations	94
6.7 Hamiltonians under time-dependent transformations	96
6.8 Group property and infinitesimal canonical transformations	97
<i>Exercises</i>	99
7 Angle-action variables	103
7.1 The simplest variables	103
7.2 The Hamiltonian in angle-action representation	106
7.3 The dependence of the angle variable upon q	110
7.4 Generating functions	112
7.5 Rotations	114
<i>Exercises</i>	116
8 Perturbation theory	122
8.1 Introduction	122
8.2 First-order perturbation theory for conservative Hamiltonian systems	125
<i>Exercises</i>	133
9 Adiabatic and rapidly oscillating conditions	141
9.1 Introduction	141
9.2 Elastic ball bouncing between two slowly moving planes	142
9.3 The linear oscillator with a slowly changing frequency	144
9.4 General adiabatic theory	149
9.5 Motion in a rapidly oscillating field: fast perturbations	153
<i>Exercises</i>	157
10 Linear Systems	163
10.1 Introduction	163
10.2 First-order systems	163
10.3 Forced linear oscillator	170
10.4 Propagators	173
10.5 Periodic conditions and linear maps	179
10.6 Linear area-preserving maps	181

Contents

10.7	Periodic forces and parametric resonance	186
	<i>Exercises</i>	191
11	Chaotic motion and non-linear maps	197
11.1	Chaotic motion	197
11.2	Maps and discrete time	198
11.3	The logistic map	199
11.4	Quadratic area-preserving maps	205
11.5	Regular and chaotic motion of Hamiltonian systems	213
	<i>Exercises</i>	214
	Appendix 1 Existence theorems	216
	Appendix 2 Integrals required for some soluble problems.	219
	Index	223