

Cambridge University Press

978-0-521-03398-5 - Statics and Kinematics with Applications to Robotics

Joseph Duffy

Copyright Information

[More information](#)

Statics and kinematics

with applications

to robotics

JOSEPH DUFFY

University of Florida



CAMBRIDGE
UNIVERSITY PRESS

Cambridge University Press

978-0-521-03398-5 - Statics and Kinematics with Applications to Robotics

Joseph Duffy

Copyright Information

[More information](#)

CAMBRIDGE UNIVERSITY PRESS

Cambridge, New York, Melbourne, Madrid, Cape Town, Singapore, São Paulo

Cambridge University Press

The Edinburgh Building, Cambridge CB2 2RU, UK

Published in the United States of America by Cambridge University Press, New York

www.cambridge.org

Information on this title: www.cambridge.org/9780521482134

© Cambridge University Press 1996

This publication is in copyright. Subject to statutory exception and to the provisions of relevant collective licensing agreements, no reproduction of any part may take place without the written permission of Cambridge University Press.

First published 1996

This digitally printed first paperback version 2006

A catalogue record for this publication is available from the British Library

Library of Congress Cataloguing in Publication data

Duffy, Joseph, 1937–

Statics and kinematics with applications to robotics / Joseph Duffy.

p. cm.

Includes index.

ISBN 0-521-48213-5 (hardcover)

1. Manipulators (Mechanism) 2. Statics. 3. Machinery, Kinematics of. 4. Robots – Motion. I. Title.

TJ211.D84 1996

95-4913

670.42'72 – dc20

CIP

ISBN-13 978-0-521-48213-4 hardback

ISBN-10 0-521-48213-5 hardback

ISBN-13 978-0-521-03398-5 paperback

ISBN-10 0-521-03398-5 paperback