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# Synthetic Differential Topology

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## Preface

The subject of synthetic differential geometry has its origins in lectures and papers by F. William Lawvere, most notably [72], but see also [74, 76]. It extends the pioneering work of Charles Ehresmann [40] and André Weil [111] to the setting of a topos [73, 55]. It is synthetic (as opposed to analytic) in that the basic concepts of the differential calculus are introduced by axioms rather than by definition using limits or other quantitative data. It attempts to capture the classical concepts of differential geometry in an intuitive fashion using the rich structure of a topos (finite limits, exponentiation, subobject classifier) in order to conceptually simplify both the statements and their proofs. The fact that the intrinsic logic of any topos model of the theory is necessarily Heyting (or intuitionistic) rather than Boolean (or classical) plays a crucial role in its development. It is well adapted to the study of classical differential geometry by virtue of some of its models.

This book is intended as a natural extension of synthetic differential geometry (SDG), in particular of the book by Anders Kock [61] to (a subject that we here call) synthetic differential topology (SDT). Whereas the basic axioms of SDG are the representability of jets (of smooth mappings) by tiny objects of an algebraic nature, those of SDT are the representability of germs (of smooth mappings) by tiny objects of a logical sort introduced by Jacques Penon [96, 94, 95]. In both cases, additional axioms and postulates are added to the basic ones in order to develop special portions of the theory.

In a first part we include those portions of topos theory and of synthetic differential geometry that should minimally suffice for a reading of the book. As an illustration of the benefits of working synthetically within topos theory we include in a second part a version of the theory of connections and sprays [28, 22] as well as one of the calculus of variations [52, 27]. The basic ax-

ioms for SDT were introduced in [20, 25, 26] and are the contents of the third part of this book. The full force of SDT is employed in the fourth part of the book and consists of an application to the theory of stable germs of smooth mappings including Mather’s theorem [20, 26, 103] and Morse theory on the classification of singularities [44, 45, 46]. The fifth part of the book recalls the notion of a well adapted model of SDG in the sense of [32, 10] and extends it to one of SDT. In this same part, and under the assumption of the existence of a well adapted model of SDT, a theory of unfoldings is given as a particular case of the general theory, unlike what is done in the classical case [110]. The sixth part of the book is devoted to exhibiting one such well adapted model of SDT, namely a Grothendieck topos  $\mathcal{G}$  constructed by Eduardo Dubuc [34] using the algebraic theory [70] of  $C^\infty$ -rings [72] and germ determined (or local) ideals. On account of the existence of a well adapted model of SDT, several classical results can be recovered. In these applications of SDG and SDT to classical mathematics, it should be noted that not only do they profit from the rich structure of a topos, not available when working in the category of smooth manifolds, but also that the results so obtained are often of a greater generality and conceptual simplicity than their classical counterparts.

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