

## *Index*

- absorption characteristic, 41
- acceleration
  - disturbing, 85
  - Keplerian, 29
  - linear, 8
  - longitudinal, 58, 78
- accumulation of momentum, 189
- ACS accuracy, 172
- action equation of motion, 299
- active attitude control, 112
- active control, 210, 214
- active damping, 117, 126
- active nutation control, 135
- active nutation damping, 225
- active wheel nutation damping, 146
- aerodynamic force, 32
- air density, 32
- altitude of
  - apogee, 65
  - geostationary orbit, 73
  - low-orbit satellite, 28, 72
  - orbit, 32
  - perigee, 65
- amplification of
  - position sensor noise, 179
  - rate sensor noise, 178
  - reaction wheel torque noise, 179
- analog sun sensor, 345
- angular dynamic equations, 88, 211
- angular momentum, 11, 88, 89
- angular motion, 88, 90
- angular velocity, 88, 101, 162
- angular velocity sensors, 175
- anomalies, eccentric, true, 18
- aphelion, 15
- apoapsis, 15
- apogee, 15
- apogee boost motor (ABM) 60, 381
- apsides, 68
- argument of perigee, 24, 28, 68
- Aries, first point of, 23
- ascending node, 23, 36
- asymptotes, 17
- atmospheric drag, 32, 72
- attitude calculation, 336
- attitude control, 163
  - gravity gradient, 112, 114
  - laws, 156
- magnetic, 188, 222
- reaction thrust, 242
- solar torque, 222, 229
- time-optimal, 195
- attitude determination hardware, 328
- attitude dynamics, 88
- attitude error, 76
- attitude kinematics, 88, 100
- attitude-maneuvering satellite, 112
- attitude maneuvers, 152
- attitude matrix, 318
- attitude sensors, 173, 174
- attitude stability, 173
- attitude transformations in space, 325
- axis of symmetry, 95
- ballistic coefficient, 33
- bandwidth of attitude control system, 180
- bang-bang control, 141, 195
- basic attitude control equation, 113, 152
- bending modes, 180
- bias attitude error, 335
- body cone, 98
- body coordinate frame, 318
- body rates estimation, 158
- Canopus, 363
- cantilever beam, 297
- cantilever natural frequency, 294
- Cape Canaveral, 73
- Cartesian coordinate system, 24, 27
- catalyst, 382
- catalytic activity, 383
- CCD matrix, 369
- central force, 12
- celestial background, 364
- celestial coordinates, 371
- celestial catalog, 365
- celestial map, 365
- celestial pole, 22
- celestial sphere, 23, 365
- center of
  - attracting body, 43
  - earth, 40
  - eccentricity circle, 55
- central force field, 12
- charge coupled device (CCD) detector, 369
- chatter, 143, 198, 201

- chemical propulsion
  - liquid, 382
  - solid, 381
- circularization of GTO, 75
- classical orbit parameters, 24, 27
- code
  - binary, 352
  - Gray, 352
- cold gas propulsion, 381
- conical section, 14
- conservation of angular momentum, 161
- conservation of energy, 10
- conservative force, 10
- constant of gravitation, 9
- control hardware, 379
- control torques, 113
- control torque saturation, 223
- coplanar transfer orbit, 69
- cosine sun detector, 345
- coupling coefficients and matrices, 310
- critical inclination, 37
- damper
  - boom articulation, 123
  - external spring boom, 123
  - magnetic hysteresis, 123
  - point mass, 123
  - wheel, 124
- damping
  - active, 126
  - all-magnetic active, 129
  - passive, 123, 146
  - passive wheel nutation, 144
- damping factor, coefficient, 123, 145
- dead zone, 140, 285
- deflection mode
  - in-plane, 309
  - out-of-plane, 309
  - torsional, 309
- denutation, 139
- despin, 139
- digital sun sensor, 351
- direction cosine error matrix, 154, 318
- direction cosine matrix, 104, 153, 318, 323
- direction cosines, 46
- discrete control, 273
- displacement equations of motion, 300
- dissipation function, 293
- disturbed Keplerian orbit, 37
- disturbing torque, 114, 132
- disturbance torques, 122, 274
- double stars, 365
- drag coefficient, 32
- drift rate, 79
- dry center of mass, 305
- dual-cone optical head, 333
- dual-cone scanner, 334
- dual-spin stabilization, 132, 148, 210
- earth albedo, 329
- earth circle, 337
- earth
  - equatorial plane, 23, 56
  - escape velocity, 16
- earth sensors, 174 , 329
  - noise amplification, 220
- earth's magnetic field, 123, 126, 186
- eccentric anomaly, 18
- eccentricity, 14, 21, 42,
- eccentricity circle, 52, 84
- eccentricity corrections, 78, 84
- eccentricity derivative, 55
- eccentricity vector, 43, 52 , 81
- eccentricity vector evolution, 55
- ecliptic plane, 23, 45
- ecliptic pole , 48
- eigenaxis rotation, 195
- eigenfrequency, 295
- eigenvalue, 92 , 299
- eigenvector, 92, 299
- eigenvector of rotation, 323
- electric propulsion, 385
- ellipsoid
  - of inertia, 93
  - of momentum, 94
- emission spectra, 363
- energy
  - kinetic, 9
  - potential, 9
- energy constant, 16
- energy dissipation, 99, 138, 149, 244
  - rate, 138
- energy sink, 138
- epoch, 23
- equatorial plane, 22, 37, 42, 73
- escape velocity (from circular orbit), 16
- Euler angle errors, 153
- Euler angle rotation, 319
- Euler angles, 101, 104, 110
- Euler angular rates, 153
- Euler axis of rotation, 155, 188, 323
- Euler–Hill equations, 57
- Euler's moment equation, 95, 145
- evolution of the eccentricity vector, 50
- evolution of the inclination vector, 43
- external disturbances, 275
- external torque, 107
- field of view (FOV), 329, 350, 373
- first point of the Aries, 23
- flexibility coefficients, 298
- flexibility matrix, 298

- flexible solar array, 291  
 flexural rigidity, 297  
 flux of light, 357  
 focus, 8, 15  
 force-deflection equation, 297  
 frequency of oscillation, 117  
 friction, 394  
 fuel consumption, 64, 70, 136, 143  
 fuel tank, 302  
 Gauss planetary equations, 30  
 generalized coordinates, 293  
 generalized forces, 293  
 geocentric inertial system, 22, 23  
 geocentric latitude, 35  
 geographical  
     latitude, 36, 68, 73  
     longitude, 35, 78  
 geomagnetic equator, 187  
 geopotential function, 35  
 geostationary, 28, 42, 73  
 geostationary orbit corrections, 80  
 geosynchronous, 42, 73  
 gravitational  
     attraction field, 17  
     force, 44  
     potential, 34, 37  
 gravity gradient, 112  
     attitude control, 114  
     characteristic equation, 114  
     moments, 108  
     stabilization, 112, 122, 126  
     vector, 109  
 Gray binary code, 351  
 Greenwich meridian, 43  
 hardware  
     attitude determination, 174, 328  
     control, 160, 379  
 harmonic coefficients, 14  
     sectoral, 35  
     spherical, 34  
     tesseral, 35  
     zonal, 35  
 harmonic motion, 49, 117  
 Hill equations, 58  
 Hohmann transfer, 70  
 horizon-crossing sensor, 330  
 horizon sensor, 330  
 hyperbolic orbit, 17  
 image dissector, 367  
 immunity to sensor noise, 246  
 impulsive force, 59  
 impulsive thrust, 64  
 inclination, 24, 42  
     angle, 28  
     circle, 82  
     correction, 74, 82  
     station keeping, 80, 81  
     zeroing, 74  
 inclination derivatives, 49  
 inclination drift, 41  
 inclination vector , 43, 82  
     evolution, 43  
 inertia matrix, 88  
 inertial coordinate system, 22, 25  
 inertial frame, 26  
 inertial measuring unit (IMU), 181  
 inertial reference frame, 26  
 influence coefficient, 292  
 infrared earth sensor, 329  
 infrared static earth sensor, 343  
 in-plane deflection mode, 309  
 integrator, 278  
 inverse square law of force, 9, 10  
 ion thruster, 386  
 Keplerian acceleration, 29  
 Keplerian orbit, 8, 12  
 Kepler's laws, 8, 19  
 Kepler's time equation, 20  
 Kourou, 73  
 Lagrange's equations, 45, 293  
 Lagrange's method, 293  
 Lagrange's planetary equation, 33  
 latch valves, 384  
 launch site, 73, 74  
 law of areas , 19  
 Legendre polynomials, 35, 41  
 linearized attitude dynamics equations of  
     motion, 108, 312  
 line of apsides, 65  
 line of nodes, 37  
 liquid slosh, 180, 301  
 local coordinate system, 25  
 longitude station keeping, 85  
 longitudinal acceleration, 56, 78  
 longitudinal drift rate, 79  
 lunar pole, 48  
 magnetic active damping, 129  
 magnetic attitude control, 185  
 magnetic control dipole, 126  
 magnetic field, 123, 126, 128  
 magnetic moments, 397  
 magnetic torquers (torqrods), 126, 187, 397  
 magnetic torque equation, 191  
 magnetic unloading of momentum, 189  
 magnetotorquers, 397  
 magnitude  $m$  of a star, 357  
 major axis, 16, 92

- mask detector, 349  
 mass matrix, 298  
 massless cantilever beam, 297  
 mean anomaly, 20  
 mean longitude, 43  
 mean motion, 20  
 mean radius of earth, 35  
 minimum impulse bit, 245, 284  
 minimum torque impulse bit, 285  
 minor axis, 92  
 modal frequency, 294  
 modeling liquid slosh, 301  
 modeling solar panels, 291  
 modulator  
     pulse width, (PW), 273  
     pulse width-pulse frequency (PWPF), 266, 270  
     pseudo rate (PR), 270  
 Molniya orbit, 37  
 moment of inertia, 89  
     maximum, 92  
     minimum, 92  
     principal, 92  
     about spin axis, 90  
 moment of momentum, 11  
 momentum axis of orbit, 25  
 momentum bias, 212,  
 momentum-biased attitude stabilization, 161, 210  
 momentum accumulation, 165  
 momentum  
     linear, 8,  
     angular, 11, 88  
 momentum-biased satellite, 217  
 momentum bias stabilization, 150  
 momentum capacity, 206  
 momentum dumping, 165, 241  
     magnetic, 194  
     reaction, 241, 250  
 momentum exchange device, 107, 160, 393  
     control moment gyro, 161  
     momentum wheel, 107, 161, 237  
     reaction wheel, 161  
 momentum management, 169  
 momentum wheel, 161, 211, 393  
 monopropellant propulsion system, 382  
 moon's orbit, 45, 48  
 multi-mass modeling, 296, 308  
 multi-mass sloshing model, 308  
  
 nadir, 214, 331  
 nadir-pointing stabilized satellite, 120  
*n*-body problem, 39  
 natural eccentricity radius, 55, 84  
 natural frequency, 180  
 natural frequency of oscillation, 300, 301  
  
 Newton's laws, 8  
     second law of motion, 39  
 node line, 24,  
 noise amplification, 178, 220  
 nonconservative perturbing forces, 28  
 nonhomogeneity of the earth, 34  
 nonspinning satellite  
     dynamic equations of, 107  
     kinematic equations of, 100  
 nonviscous liquid, 302  
 North-South station keeping, 81  
 nozzle throat, 381  
 nutation  
     damper, 146  
     destabilization, 99  
     instability, 100  
     stability, 100,  
     nutation angle, 98, 133  
     nutation frequency, 136, 212, 220  
     nutational motion, 132  
  
 oblateness effects of the earth, 34, 329  
 onboard star catalog, 370  
 one-vibrating mass model, 302  
 open-loop gain, 313  
 operational constraints, 67  
 optical scanning mechanism, 330, 367  
 optical sensor head, 349  
 orbital  
     adjustment, 65, 78  
     corrections, 80  
     frequency, 212  
     maneuvers, 64  
     period, 32  
     plane, 24, 44  
     pole, 24, 43, 80  
     rate, 117  
 orbit change  
     in-plane, 68, 75  
     multi-impulse, 70  
     out-of-plane, 75  
     single-impulse, 65  
 orbit coordinates, 25  
 orbit mechanics, 8  
 orbit parameters, 24, 32  
 orbit reference frame, 101, 105  
 orbits  
     altitude, 32  
     circular, 15  
     coaxial, 71  
     coplanar, 71  
     elliptical, 15  
     equatorial, 24  
     geostationary, 42, 73  
     geosynchronous, 42, 73  
     heliosynchronous, 36

- hyperbolic, 17
- parabolic, 16
  - sun-synchronous, 36
- oscillation frequency, 305
- osculating orbit, 29
- out-of-plane deflection mode, 309
- passive attitude control, 112
- passive dampers, 123
- passive wheel nutation damping, 144
- parabolic trajectory, 78
- parasitic disturbing torques, 161
- passage time from perigee, 21
- pendulum, frequency of oscillation, 302
- periapsis, 15
- perigee, 15
  - argument, 24
  - passage, 20
- perihelion, 15
- perturbation acceleration, 29, 31, 40, 85
- perturbed
  - orbit, 28
  - equation of motion, 29
- perturbing body, 40
- perturbing forces, 28, 33, 85
- perturbing potential function, 37
- perturbing third body, 39
- photomultiplier, 367
- planetary precession, 23
- Polaris, 214, 357
- pole
  - celestial, 22
  - ecliptic, lunar, 48
  - orbital, 44, 80
- polhode, 94
- positioning accuracy, 173
- potential energy, 10, 14
- power loss, 392
- precession
  - lunar pole, 48
  - planetary, 23
- precessional motion, 22
- prime focus, 15, 18
- principal axes, 93
- principal axes of inertia, 91
- principal moments of inertia, 92
- product of inertia, 90, 225, 248
- propellant
  - control valve, 384
  - liquid, 382
  - mass, 72
  - solid, 381
- proper real orthogonal matrix, 319
- propulsion, 379
  - bipropellant, 385
  - chemical, 381
- cold gas, 381
- electric, 385
- liquid, 382
- monopropellant, 382
- solid propellant, 381
- propulsion rocket equation, 380
- pseudoinverse matrix, 160
- pseudo rate (PR) modulator, 270
- pulsed controller, 273
- pulsed reaction system, 273
- pulse width modulation, 265, 273
- pulse width-pulse frequency modulation, 265, 267
- pulsing mode, 260
- quaternion, 104 , 322
- quaternion error vector, 156
- quaternion method, 322
- quaternion multiplication, 326
- quaternion vector, 104
- radiance detector, 330, 344
- radiation pressure 41
- rate
  - gyro, 158, 375
  - integrating gyro, 105, 175, 375
- rate sensor, 175, 373
- reaction control system, 140
- reaction thruster attitude control, 260
- reaction thruster, 242, 260
  - HT, LT, 385
- reaction torque, 260, 265
- reaction wheel, 161, 206, 393
- reciprocity theorem, 298
- reference coordinate system, frame, 101
- relative acceleration, 58
- relative distance, 58
- relative motion, 10, 58
- restrictions on orbit changes, 69
- reticle slit pattern, 351
- right ascension, 24, 28, 43
- right-handed system, 23
- right pseudoinverse transformation, 169
- rigid body, 88, 291
  - rotation kinetic energy, 90
- roll deadbeat limit, 247
- roll-yaw attitude control, 237
- root locus, 146
- rotating frame, 102
- rotational axis, 91
- rotational kinetic energy, 90, 94
- rotational motion, 88, 238
- sampled transfer function, 284
- sampling frequency, 273
- satellite motion, 59

- scalar potential function, 34  
scanning mechanism, 330  
scanning rate, 338  
Schmidt trigger, 265,  
sectoral harmonic coefficients, 35  
secular term  
  of inclination derivative, 50  
semi-latus rectum, 14  
semimajor axis, 16, 65  
semiminor axis, 16  
sensor noise, 113, 173  
  amplification, 178, 266  
side force, 308  
sidereal angle, 42  
sidereal day, 42  
signal processing, 330, 369  
simulation, 6-DOF, 120  
single-mass structural dynamics, 293  
single-spin stabilization, 132, 144  
slosh dipole, 305  
solar  
  efficiency, 234  
  energy flux, 41  
  pressure, 28  
  radiation, 41  
  torques, 388  
  wind, 41  
solar control torques, 229, 388  
solar flaps, 230  
solar panels, 230  
solar radiation perturbing function,  
  53  
solar torque capability, 392  
space cone, 98  
specific angular momentum, 12  
specific impulse  $I_{sp}$ , 380  
spectra of a star, 357  
spherical harmonic expansion, 34  
stability of rotation, 96  
star catalog, 369  
star identification, 371  
star scanner, 366  
star sensor, 353  
  assembly, 367  
  specification, 373  
star tracking, 366  
static earth sensor, 343  
steady-state error, 278  
stellar distribution, 364  
stiffness coefficient, 292, 298  
stiffness constant, 299  
stiffness matrix, 298  
structural dynamics, 113, 291, 291  
structural model, 295, 296  
structural modeling, 291,  
sun acquisition, 350  
sun sensors, 174, 345  
  analog, 345  
  digital, 351  
  one-axis, 347  
  two-axis, 349  
sun-synchronous orbit, 36  
switching curve, 198  
tachometer, 396  
terminator, 329  
tesseral harmonic coefficients, 35, 37  
thermal emission, 329  
thermopile, 344  
third-body perturbing force, 39  
three-axes stabilized, 100  
three-body problem, 39  
thruster activation time, 263  
thrusters, 387  
  electrothermal monopropellant, 384  
  hydrazine, 383  
  ion, 386  
time delay, 200  
time derivation  
  of direction cosine matrix, 104  
  of quaternion vector, 104  
time-optimal attitude control, 195  
time response, 117, 212, 235  
time since periaxis passage, 18  
torque  
  arm, 262  
  commands, 141  
  control law, 152, 207  
  impulse bit, 245, 262  
  solar, 234, 388  
torque spectra noise, 394  
torque impulses, 273  
torque wheel, 107  
torsional deflection mode, 309  
total energy, 10, 14  
total energy per unit mass, 14  
total impulse, 380  
transfer  
  geostationary (GTO), 73, 85  
  geosynchronous, 73  
  Hohmann 70  
  orbit, 64, 71  
transformation, three-dimensional, 25  
transplanetary s/c voyage, 17  
true anomaly, 18  
two-body problem, 10  
unbalanced torque, 232  
unified propulsion system, 384  
universal constant of gravity, 9  
variable stars, 365  
variance in earth radiation, 336

*Index*

409

variation of parameters, 34

Vega, 357

velocity

angular, 59

circular, 51

radial, 31

relative, 59

vector, 8, 30

velocity change, 64, 78

velocity increment, 52

velocity loss, 64, 133

vernal equinox, 23

vibrating mass model, 302

viscosity damping coefficient, 163

visual magnitude, 363

wheel damper, 123

wheel momentum dumping, 250

wheel momentum management, 396

windmill torque, 231

work and energy, 9

yaw error, 217

yaw measurement, 215

zero-bias momentum system, 190