Nonlinear Dynamics: A Primer

This book provides a systematic and comprehensive introduction to the study of nonlinear dynamical systems, in both discrete and continuous time, for nonmathematical students and researchers working in applied fields including economics, physics, engineering, biology, statistics and linguistics. It includes a review of linear systems and an introduction to the classical theory of stability, as well as chapters on the stability of invariant sets, bifurcation theory, chaotic dynamics and the transition to chaos. In the final chapters the authors approach the study of dynamical systems from a measure-theoretical point of view, comparing the main notions and results to their counterparts in the geometrical or topological approach. Finally, they discuss the relations between deterministic systems and stochastic processes.

The book is part of a complete teaching unit. It includes a large number of pencil and paper exercises, and an associated website offers, free of charge, a Windows-compatible software program, a workbook of computer exercises coordinated with chapters and exercises in the book, answers to selected book exercises, and further teaching material.

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> To the memory of my father who taught me to love books

To my mother and father

Contents

Preface		page xi
1	Statics and dynamics: some elementary concepts	1
1.1	A static problem	1
1.2	A discrete-time dynamic problem	3
1.3	A continuous-time dynamic problem	7
1.4	Flows and maps	11
Exercises		
2	Review of linear systems	22
2.1	Introduction	22
2.2	General solutions of linear systems in continuous time	25
2.3	Continuous systems in the plane	34
2.4	General solutions of linear systems in discrete time	43
2.5	Discrete systems in the plane	47
2.6	An economic example	52
Appendix: phase diagrams		56
Exercises		
3	Stability of fixed points	66
3.1	Some formal definitions of stability	66
3.2	The linear approximation	71
3.3	The second or direct method of Lyapunov	76
Appendix A: general economic equilibrium		85
Appendix B: optimal economic growth		92
Appendix C: manifolds and tangent spaces		98
Exercises		

viii	Contents	
4	Invariant and attracting sets, periodic and	
	quasiperiodic orbits	104
4.1	Invariant and limit sets	105
4.2	Stability and attractiveness of general sets	110
4.3	Attracting sets and attractors	114
4.4	Periodic orbits and their stability	118
4.5	Quasiperiodic orbits	126
App	endix: conservative and dissipative systems	128
Exercises		
5	Local bifurcations	133
5.1	Introduction	133
5.2	Centre manifold theory	134
5.3	Local bifurcations for flows	139
5.4	Local bifurcations for maps	151
5.5	Bifurcations in two-dimensional maps	160
Exercises		161
6	Chaotic sets and chaotic attractors	163
6.1	Basic definitions	164
6.2	Symbolic dynamics and the shift map	166
6.3	Logistic map with $\mu > 2 + \sqrt{5}$	171
6.4	Smale horseshoe	173
6.5	Tent map and logistic map	176
6.6	Doubling maps	178
6.7	Chaotic attractors	180
6.8	The Lorenz model	182
Exer	cises	189
7	Characteristic exponents, fractals, homoclinic orbits	193
7.1	Lyapunov characteristic exponents	193
7.2	Fractal dimension	198
7.3	Horseshoes and homoclinic orbits	204
Exer	rcises	211
8	Transition to chaos	214
8.1	Period-doubling route to chaos	214
8.2	Intermittency	222
8.3	Crises	226
8.4	Quasiperiodicity and chaos	232
Exer	cises	235

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Cambridge University Press
0521551862 - Nonlinear Dynamics: A Primer - Alfredo Medio and Marji Lines
Frontmatter/Prelims
Moreinformation

	Contents	ix
9	The ergodic approach	237
9.1	Ergodic measures	238
9.2	Lyapunov characteristic exponents revisited	247
9.3	Natural, absolutely continuous, SBR measures	249
9.4	Attractors as invariant measures	252
9.5	Predictability, entropy	253
9.6	Isomorphism	260
9.7	Aperiodic and chaotic dynamics	261
9.8	Mixing	265
Appendix: Shannon's entropy and Khinchin's axioms		267
Exercises		268
10	Deterministic systems and stochastic processes	270
10.1	Bernoulli dynamics	270
10.2	Markov shifts	276
10.3	α -congruence	277
Furt	her reading	282
Bibli	ography	287
Subj	ect index	295

Preface

Over the years we have had the rare opportunity to teach small classes of intelligent and strongly motivated economics students who found nonlinear dynamics inspiring and wanted to know more. This book began as an attempt to organise our own ideas on the subject and give the students a fairly comprehensive but reasonably short introduction to the relevant theory. Cambridge University Press thought that the results of our efforts might have a more general audience.

The theory of nonlinear dynamical systems is technically difficult and includes complementary ideas and methods from many different fields of mathematics. Moreover, as is often the case for a relatively new and fast growing area of research, coordination between the different parts of the theory is still incomplete, in spite of several excellent monographs on the subject. Certain books focus on the geometrical or topological aspects of dynamical systems, others emphasise their ergodic or probabilistic properties. Even a cursory perusal of some of these books will show very significant differences not only in the choice of content, but also in the characterisations of some fundamental concepts. (This is notoriously the case for the concept of attractor.)

For all these reasons, any introduction to this beautiful and intellectually challenging subject encounters substantial difficulties, especially for nonmathematicians, as are the authors and the intended readers of this book. We shall be satisfied if the book were to serve as an access to the basic concepts of nonlinear dynamics and thereby stimulate interest on the part of students and researchers, in the physical as well as the social sciences, with a basic mathematical background and a good deal of intellectual curiosity.

The book includes those results in dynamical system theory that we deemed most relevant for applications, often accompanied by a commonsense interpretation. We have also tried, when necessary, to eliminate the

xii

Preface

confusion arising from the lack of consistent and universally accepted definitions of some concepts. Full mathematical proofs are usually omitted and the reader is referred either to the original sources or to some more recent version of the proofs (with the exception of some 'canonical' theorems whose discussion can be found virtually in any textbook on the subject).

We devote an unusually large space to the discussion of stability, a subject that in the past played a central role in the theory of differential equations and related applied research. The fundamental monographs on stability were published in the 1960s or early 1970s yet there is surprisingly little reference to them in modern contemporary research on dynamical systems. We have tried to establish a connection between the classical theory of stability and the more recent discussions of attracting sets and attractors.

Although the word 'chaos' does not appear in the title, we have dedicated substantial attention to chaotic sets and attractors as well as to 'routes to chaos'. Moreover, the geometric or topological properties of chaotic dynamics are compared to their measure-theoretic counterparts.

We provide precise definitions of some basic notions such as neighbourhood, boundary, closure, interior, dense set and so on, which mathematicians might find superfluous but, we hope, will be appreciated by students from other fields.

At an early stage in the preparation of this book, we came to the conclusion that, within the page limit agreed upon with the publisher, we could not cover both theory and applications. We squarely opted for the former. The few applications discussed in detail belong to economics where our comparative advantages lie, but we emphasised the multi-purpose techniques rather than the specificities of the selected models.

The book includes about one hundred exercises, most of them easy and requiring only a short time to solve.

In 1992, Cambridge University Press published a book on Chaotic Dynamics by the first author, which contained the basic concepts of chaos theory necessary to perform and understand numerical simulations of difference and differential equations. That book included a user-friendly software program called DMC (Dynamical Models Cruncher). A refurbished, enlarged and Windows-compatible version of the program is available, at no cost, from the webpage

<http://uk.cambridge.org/economics/catalogue/0521558743> along with a workbook of computer exercises coordinated with the 'paper and pencil' exercises found in the book. The webpage will also be used to circulate extra exercises, selected solutions and, we hope, comments and criticisms by readers.

Preface

xiii

We take this opportunity to give our warm thanks to those who, in different capacities and at different times, helped us complete this book.

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