Index

adaptation 3–4, 45
adaptive control 55
direct 163
for systems with nonlinear parametrization 151–152, 158, 202
non-dominating 157, 202
of interconnected systems 192
adaptive integrator back-stepping 61
adaptive observer 214
adaptive-observer canonical form
  Bastin–Gevers 358
  Marino–Tomei 360
adaptive regulation 11, 188
adaptive system 47–50
algorithms of adaptation
  in finite form 164
  minimax 71
  velocity gradient 56
  virtual 163, 165
attracting set 17
attractor 20, 265
Barbalat’s lemma 20
bottle-neck theorem 101
controller 106
  adaptive 55
  dominating 71, 79
  convergence 37
  exponential 37
  non-uniform 117
dynamics
  separable in space-time 125
  target 156
  unmodeled 156, 193, 214
embedding technique 170
Hindmarsh–Rose equations 211, 305, 351
Hodgkin–Huxley equations 351
input–output margin 87
input–state margin 87
interconnection
  feedback 96, 108
  parallel 95, 98
  serial 95, 98
majorizing
  function 99
  mapping 98, 100
metastability 300
method
  of adaptive integrator back-stepping 61
  of Lyapunov functions 28
  of the velocity gradient 56
  of the virtual algorithm of adaptation 163
Meyer–Kalman–Yakubovich lemma 387
models
  error models 71
  lower-triangular 51, 174
  Morris–Lecar equations 5, 381
non-uniform small-gain theorem 117, 120
observability 353, 354
operator
  input–output 87
  input–state 87
parameter identification 207
parameter reconstruction 213
persistency of excitation 35, 208
  nonlinear 209
  uniform 209
  weak 218
problem of adaptation 160–163
  according to L. Zadeh 52
  according to R. Bellman 51
  according to V. Yakubovich 53
separation principle 84, 105, 108
set
  attracting 17
  asymptotically stable in the sense of Lyapunov 26
  backward-invariant 16
closed 17
forward-invariant 16
invariant 15
stable in the sense of Lagrange 90
stable in the sense of Lyapunov 26
stable in the sense of Poisson 204
weakly attracting 19, 266
$\omega$-limit 109
small-gain theorem 92
stability
asymptotic 24, 26
input–output–state 94
input-to-output 23, 91, 92
input-to-state 23, 93
integral, input-to-state 93
Lagrange 90

Lyapunov 23, 24, 26
output–state 94
Poincaré 23–25
Poisson 23, 27, 204
Practical, input-to-output 93
steady-state characteristic 123
system 85
complete 88
extremal 45
realizable 88
template matching 294, 310
$\omega$-limit point 109, 117
$\omega$-limit set 109, 117